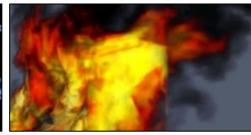


Exceptional service in the national interest





$$\int_{a,\sigma^{2}} T(x) \cdot \frac{\partial}{\partial \theta} f(x,\theta) dx = M \left(T(\xi) \cdot \frac{\partial}{\partial \theta} \ln U(\xi) \right)$$



Kokkos Ecosystem: runtime, math library, tools

Unclassified Unlimited Release

Luc Berger-Vergiat, - Center for Computing Research
Sandia National Laboratories/NM





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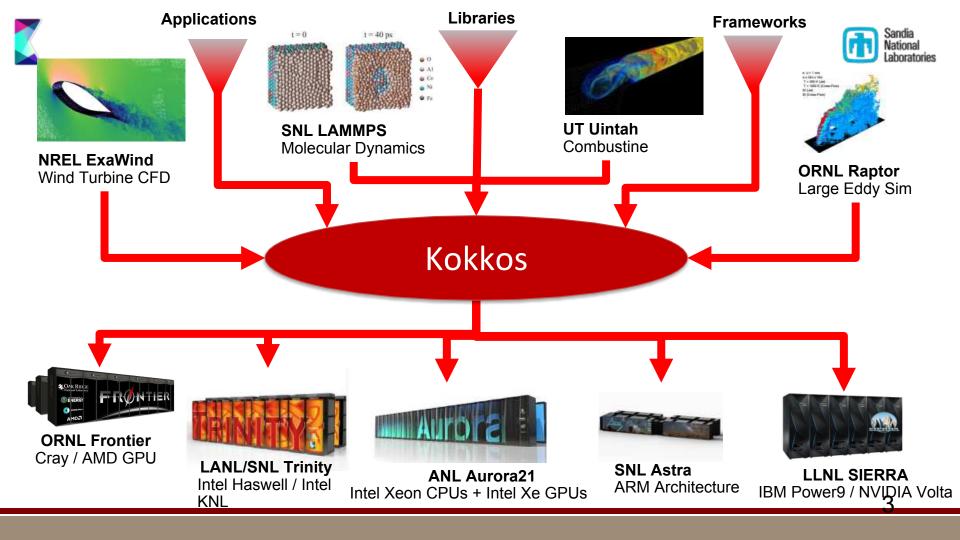


Cost of Porting Code



10 LOC / hour ~ 20k LOC / year

- Optimistic estimate: 10% of an application is modified to adopt an on-node Parallel Programming Model
- Typical Apps: 300k 600k Lines
 - 500k x 10% => Typical App Port 2.5 Man-Years
- Large Scientific Libraries
 - E3SM: 1,000k Lines x 10% => 5 Man-Years
 - Trilinos: 4,000k Lines x 10% => 20 Man-Years





What is Kokkos?

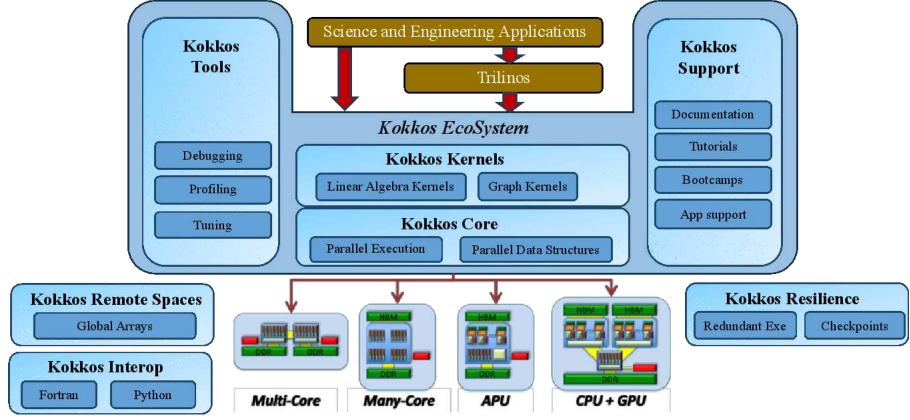


- A C++ Programming Model for Performance Portability
 - Implemented as a template library on top of CUDA, OpenMP, HPX, ...
 - Aims to be descriptive not prescriptive
 - Aligns with developments in the C++ standard
- Expanding solution for common needs of modern science/engineering codes
 - Math libraries based on Kokkos
 - Tools which enable insight into Kokkos
- It is Open Source
 - Maintained and developed at https://github.com/kokkos
- It has many users at wide range of institutions.



Kokkos EcoSystem







Transitioning To Community Project



Kokkos Core: 15 Developers (8 SNL)





- More code contributions from non-SNI
 - >50% of commits from non-Sandians
- Sandia leads API design
- Other labs lead backend implementations
- Other subprojects largely by Sandia so far







Kokkos Core: C.R. Trott, N. Ellingwood, D. Ibanez, J. Miles, D. Hollman, V. Dang, Jan Ciesko, J. Wilke, L. Cannada,

H. Finkel, N. Liber, D. Lebrun-Grandie, B. Turcksin, J. Madsen, D. Arndt, J. Madsen, R. Gayatri

former: H.C. Edwards, D. Labreche, G. Mackey, S. Bova, D. Sunderland,

Kokkos Kernels: S. Rajamanickam, L. Berger, V. Dang, N. Ellingwood, E. Harvey, B. Kelley, K. Kim, C.R. Trott, J. Wilke, S. Acer

D. Poliakoff, S. Hammond, C.R. Trott, D. Ibanez, S. Moore, L. Cannada **Kokkos Tools:**

C.R. Trott, G. Shipman, G. Lopez, G. Womeldorff, **Kokkos Support:**

former: **H.C. Edwards**, D. Labreche, Fernanda Foertter



Kokkos Uptake



ECP Critical Dependencies

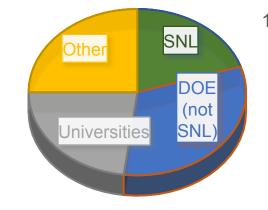
MPI	60
LLVM	57
C++	41
OpenMP	34
LAPACK	24
CUDA	22
Fortran	21
HDF5	21
BLAS	21
Kokkos	18
С	14
ALPINE	12

hypre	11
DAV-SDK	11
VTK-m	11
Trilinos	10
ADIOS	8
SPACK	8
SCALAPACK	8 7
FFT	7
OpenACC	7
MPI-IO	6
PnetCDF	6
Tau	6

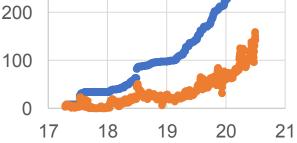
Kokkos Slack Users



- 90 Institutions
- Every continent
 - (-Antarctica)
- Doubles every year





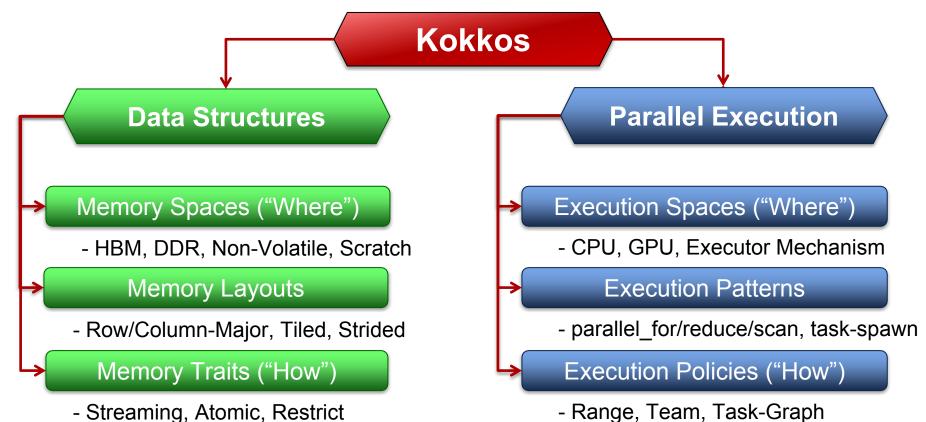


- Total membership
- Weekly active members



Kokkos Core Abstractions



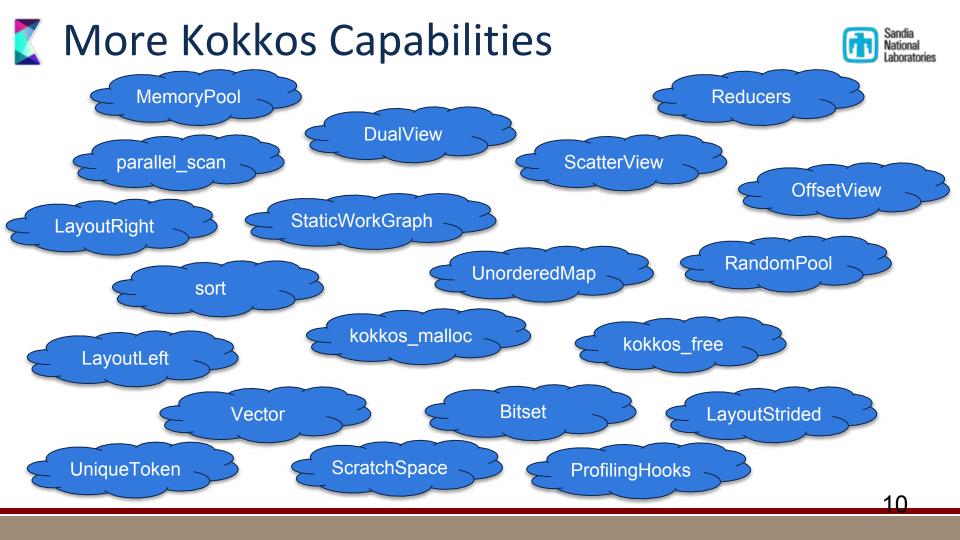




Kokkos Core Capabilities



Concept	Example
Parallel Loops	parallel_for(N, KOKKOS_LAMBDA (int i) {BODY });
Parallel Reduction	<pre>parallel_reduce(RangePolicy<execspace>(0,N), KOKKOS_LAMBDA (int i, double& upd) { BODY upd += }, Sum<>(result));</execspace></pre>
Tightly Nested Loops	<pre>parallel_for(MDRangePolicy<rank<3> > ({0,0,0},{N1,N2,N3},{T1,T2,T3}, KOKKOS_LAMBDA (int i, int j, int k) {BODY});</rank<3></pre>
Non-Tightly Nested Loops	<pre>parallel_for(TeamPolicy<schedule<dynamic>>(N, TS), KOKKOS_LAMBDA (Team team) { COMMON CODE 1 parallel_for(TeamThreadRange(team, M(N)), [&] (int j) { INNER BODY}); COMMON CODE 2 });</schedule<dynamic></pre>
Task Dag	task_spawn(TaskTeam(scheduler , priority), KOKKOS_LAMBDA (Team team) { BODY });
Data Allocation	View <double**, layout,="" memspace=""> a("A",N,M);</double**,>
Data Transfer	deep_copy(a,b);
Atomics	atomic_add(&a[i],5.0); View <double*,memorytraits<atomicaccess>> a(); a(i)+=5.0;</double*,memorytraits<atomicaccess>
Exec Spaces	Serial, Threads, OpenMP, Cuda, HPX (experimental), HIP (experimental), OpenMPTarget (experimental)





Example: Conjugent Gradient Solver



- Simple Iterative Linear Solver
- For example used in MiniFE
- Uses only three math operations:
 - Vector addition (AXPBY)
 - Dot product (DOT)
 - Sparse Matrix Vector multiply (SPMV)
- Data management with Kokkos Views:

```
View<double*, HostSpace, MemoryTraits<Unmanaged> > h x(x in, nrows);
View<double*> x("x",nrows);
deep copy(x,h x);
```



CG Solve: The AXPBY



- Simple data parallel loop: Kokkos::parallel for
- Easy to express in most programming models
- Bandwidth bound
- Serial Implementation:

```
void axpby(int n, double* z, double alpha, const double* x,
                  double beta, const double* y) {
 for(int i=0; i<n; i++)
  z[i] = alpha*x[i] + beta*y[i];
                  Parallel Pattern: for loop
```

Kokkos Implementation:

```
void axpby(int n, View<double*> z, double alpha, View<const double*> x,
                     double beta, View<const double*> v) {
 parallel_for("AXpBY", n, KOKKO$_LAMBDA ( const int i) {
  z(i) = alpha*x(i) + beta*y(i);
```

String Label: Profiling/Debugging

Execution Policy: do n iterations

Loop Body

Iteration handle: integer index



CG Solve: The Dot Product



- Simple data parallel loop with reduction: Kokkos::parallel reduce
- Non trivial in CUDA due to lack of built-in reduction support
- Bandwidth bound
- Serial Implementation:

```
double dot(int n, const double* x, const double* y) {
 double sum = 0.0:
 for(int i=0; i<n; i++)
                                           Parallel Pattern: loop with reduction
  sum += x[i]*y[i];
 return sum;
                                                            Iteration Index + Thread-Local Red. Variable
```

Kokkos Implementation:

```
double dot(int n, View<const double*> x, View<const double*> y) {
 double x dot y = 0.0;
 parallel_reduce("Dot",n, KOKKOS_LAMBDA (const inti,double& sum) {
  sum += x[i]*y[i];
 }, x_dot_y);
 return x dot y;
```



CG Solve: Sparse Matrix Vector Multiply The National Laboratories



- Loop over rows
- Dot product of matrix row with a vector
- Example of Non-Tightly nested loops
- Random access on the vector (Texture fetch on GPUs)

Outer loop over matrix rows

```
void SPMV(int nrows, const int* A row offsets, const int* A cols,
       const double* A vals, double* y, const double* x) {
 or(int row=0; row<nrows; ++row) {
  double sum = 0.0;
  int row_start=A_row_offsets[row];
  int row_end=A_row_offsets[row+1];
  for(int i=row start; i<row end; ++i) {
   sum += A vals[i]*x[A cols[i]];
  y[row] = sum;
```

Inner dot product row x vector



CG Solve: Sparse Matrix Vector Multiply 🛅 Sandia laboratories

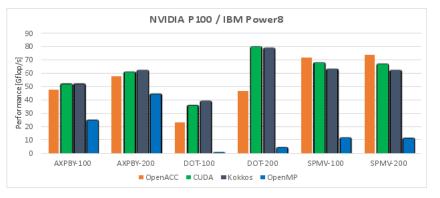


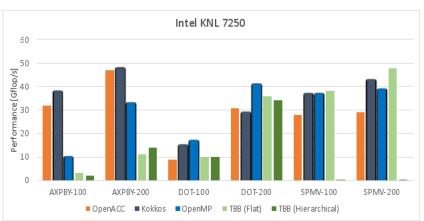
```
void SPMV(int nrows, View<const int*> A row offsets,
      View<const int*> A cols, View<const double*> A vals,
      View<double*> y,
      View const double*, Memory Traits Random Access >> x) {
                                                                                        Enable Texture Fetch on x
 // Performance heuristic to figure out how many rows to give to a team
 int rows per team = get row chunking(A row offsets);
 parallel for("SPMV:Hierarchy", TeamPolicy< Schedule< Static > >
   ((nrows+rows per team-1)/rows per team,AUTO,8),
  KOKKOS LAMBDA (const TeamPolicy<>::member type& team) {
  const int first row = team.league rank()*rows per team;
  const int last row = first row+rows per team<nrows? first row+rows per team: nrows;
  parallel for(TeamThreadRange(team, first row, last row), [&] (const int row)
   const int row start=A row offsets[row];
                                                                                                               Row x Vector dot product
   const int row_length=A_row_offsets[row+1]-row start;
   double v row:
   parallel reduce(ThreadVectorRange(team,row length),[&] (const int i, double& sum) {
    sum += A vals(i+row start)*x(A cols(i+row start));
    , v_row);
   y(row) = y row;
                                                                                   Team Parallelism over Row Worksets
         Distribute rows in workset over team-threads
```

CG Solve: Performance



- Comparison with other Programming Models
- Straight forward implementation of kernels
- OpenMP 4.5 is immature at this point
- Two problem sizes: 100x100x100 and 200x200x200 elements



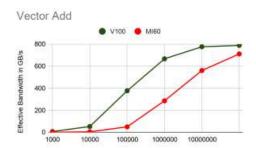


AMD Support Status

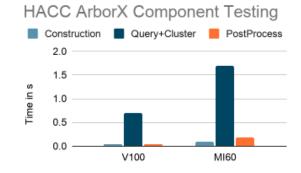
Sandia National Laboratories

Frontier/El Capitan: HIP and OpenMP 5

- Primary development of HIP at ORNL
- Most Capabilities ready
- PR testing for Kokkos on AMD GPUs in place
- ArborX, Cabana, LAMMPS working with HIP
- Trilinos linear solvers are read
- Mesh and discretization next (support ExaWind/EMPIRE)







We are largely using our own machines, with the public software stack from Intel and AMD.

Kokkos 3.3 (Dec 2020):

- HIP is largely feature complete Kokkos 3.4 (Feb/March 2021):
- OpenMP Target largely feature complete

Aurora Support Status





Programming Models: DPC++/SYCL + OpenMP 5

- Primary work for DPC++ at ANL and ORNL
 - Shifted ORNL team members from HIP to DPC++ since HIP is in much better shape
- DPC++/SYCL was long blocked by compiler issues
 - Worked with Intel to get those fixed
 - Now primary capabilities are merged to develop branch
- PR testing DPC++/SYCL in place
 - Intel DPC++/SYCL testing is done on NVIDIA GPUs ...
 - Leverages clang capability to target different backend

We are largely using our own machines (not ECP EAS), with the public software stack from Intel and AMD.

Kokkos 3.3 (Dec 2020):

- OpenMP Target and DPC++ have most primary capabilities working Kokkos 3.4 (Feb/March 2021):
- OpenMPTarget and DPC++/SYCL are largely feature complete



Kokkos Support



- The Kokkos Lectures
 - 8 lectures covering most aspects of Kokkos
 - 15 hours of recordings
 - > 500 slides
 - >20 exercises
- Extensive Wiki
 - API Reference
 - Programming Guide
- Slack as primary direct support

https://kokkos.link/the-lectures

- Module 1: Introduction
 - Introduction, Basic Parallelism, Build System
- Module 2: Views and Spaces
 - Execution and Memory Spaces, Data Layout
- Module 3: Data Structures and MDRangePolicy
 - Tightly Nested Loops, Subviews, ScatterView,...
- Module 4: Hierarchical Parallelism
 - Nested Parallelism, Scratch Pads, Unique Token
- Module 5: Advanced Optimizations
 - Streams, Tasking and SIMD
- Module 6: Language Interoperability
 - Fortran, Python, MPI and PGAS
- Module 7: Tools
 - Profiling, Tuning, Debugging, Static Analysis
- Module 8: Kokkos Kernels
 - Dense LA, Sparse LA, Solvers, Graph Kernels



Kokkos Kernels



- BLAS, Sparse and Graph Kernels on top of Kokkos and its View abstraction
 - Scalar type agnostic, e.g. works for any types with math operators
 - Layout and Memory Space aware
- Can call vendor libraries when available/beneficial
- Views contain size and stride information => Interface is simpler

```
// BLAS
int M,N,K,LDA,LDB; double alpha, beta; double *A, *B, *C;
dgemm('N','N',M,N,K,alpha,A,LDA,B,LDB,beta,C,LDC);
// Kokkos Kernels
double alpha, beta; View<double**> A,B,C;
gemm('N','N',d,lpha,A,B,beta,C);
```

Interface to call Kokkos Kernels at the teams level (e.g. in each CUDA-Block)

```
parallel_for("NestedBLAS", TeamPolicy<>(N,AUTO), KOKKOS_LAMBDA (const team_handle_t& team_handle) {
    // Allocate A, x and y in scratch memory (e.g. CUDA shared memory)
    // Call BLAS using parallelism in this team (e.g. CUDA block)
    gemv(team_handle,'N',alpha,A,x,beta,y)
});
```

Example: CG Kokkos Kernels version



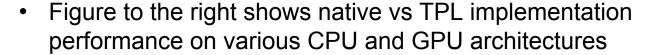
Using Kokkos Kernels sparse and dense linear algebra simplifies CG implementation greatly

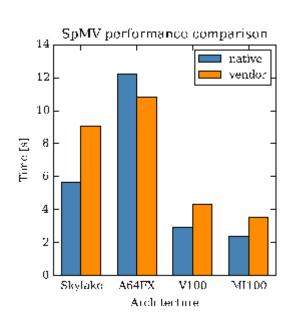
```
double toletance = 0.0; int iteration = 0;
while (tolerance < norm res && iteration < 100) {
 std::cout << "Running CG iteration " << iteration
       << ", current resnorm = " << norm res << '\n';
 /* Ap = A * p */ KokkosSparse::spmv("N", 1, crsMat, pAll, 0, Ap);
 Space().fence();
 /* pAp dot = dot(Ap, p) */ const double pAp dot = KokkosBlas::dot(p, Ap);
 double alpha = old rdot / pAp dot;
 /* x += alpha * p; */ KokkosBlas::axpby(alpha, p, 1.0, x vector);
 /* r += -alpha * Ap; */ KokkosBlas::axpby(-alpha, Ap, 1.0, r);
 const double r dot = KokkosBlas::dot(r,r);
 const double beta = r dot / old rdot;
 /* p = r + beta * p ; */ KokkosBlas::axpby(1.0, r, beta, p);
 norm res = sqrt(old rdot = r dot);
 std::cout << "\tnorm res:" << norm res << " old rdot:" << old rdot<< std::endl;
 ++iteration:
```

Kokkos Kernels SpMV performance



- SpMV native implementation is specialized for:
 - Serial runs
 - OpenMP runs
 - GPU runs
 - Single vs. Multiple vectors
- Allows users to select following vendor TPLs
 - cuSPARSE
 - MKL
 - ArmPL in test only
 - rocSparse (PR in progress)







Kokkos Tools

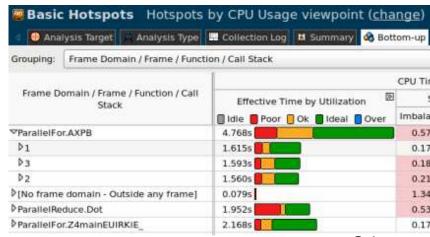


- Profiling
 - New tools are coming out
 - Worked with NVIDIA to get naming info into their system
- Auto Tuning (Under Development)
 - Internal variables such as CUDA block sizes etc.
 - User provided variables
 - Same as profiling: will use dlopen to load external tools
- Debugging (Under Development)
 - Extensions to enable clang debugger to use Kokkos naming information
- Static Analysis (Under Development)
 - Discover Kokkos anti patterns via clang-tidy

Kokkos-Tools Profiling & Debugging



- Performance tuning requires insight, but tools are different on each platform
- KokkosTools: Provide common set of basic tools + hooks for 3rd party tools
- Common issue: abstraction layers obfuscate profiler output
 - Kokkos hooks for passing names on
 - Provide Kernel, Allocation and Region
- No need to recompile
 - Uses runtime hooks
 - Set via env variable





Kokkos Tools Integration with 3rd Party



- Profiling Hooks can be subscribed to by tools, and currently have support for TAU, Caliper, Timemory, NVVP, Vtune, PAPI, and SystemTAP, with planned CrayPat support
- HPCToolkit also has special functionality for models like Kokkos, operating outside of this callback system

TAU Example:

Name =	Exclusive TIME	Inclusive TIME	Calls	Child Calls			
TAU application	0.143	96.743	1	83.			
■Comm::exchange	0.001	0.967	6	142			
Comm::exchange_halo	0.001	4.702	6	184			
Comm:update_halo	0.004	31.347	95	1,330			
■Kokkos::parallel_for CommMPI::halo_update_pack [device=0]	0.002	0.506	190	190			
Kokkos::parallel_for CommMPI::halo_update_self [device=0]	0.003	0.597	380	380			
Kokkos::parallel_for CommMPI::halo_update_unpack [device=0]	0.002	0.97	190	190			
■MPI_Irecy()	0.001	0.001	190				
■MPI_Send()	29.268	29.268	190				
■MPI_Wait()	0.001	0.001	190				
■OpenMP_Implicit_Task	0.041	1.985	760	760			
OpenMP_Parallel_Region parallel_for <kokkos::rangepolicy<commmpi::ta< p=""></kokkos::rangepolicy<commmpi::ta<>	0	0.504	190	190			
OpenMP_Parallel_Region parallel_for <kokkos::rangepolicy<commmpi::ta< td=""><td>0.08</td><td>0.968</td><td>190</td><td>190</td></kokkos::rangepolicy<commmpi::ta<>	0.08	0.968	190	190			
OpenMP_Parallel_Region void Kokkos::parallel_for <kokkos::rangepolicy< p=""></kokkos::rangepolicy<>	0.001	0.594	380	380			
OpenMP_Sync_Region_Barrier parallel_for <kokkos::rangepolicy<commmi< td=""><td>0.489</td><td>0.489</td><td>190</td><td></td></kokkos::rangepolicy<commmi<>	0.489	0.489	190				
OpenMP_Sync_Region_Barrier parallel_for <kokkos::rangepolicy<commmi< p=""></kokkos::rangepolicy<commmi<>	0.875	0.875	190				
OpenMP Sync Region Barrier void Kokkos::parallel_for <kokkos::rangepol< td=""><td>0.58</td><td>0.58</td><td>380</td><td></td></kokkos::rangepol<>	0.58	0.58	380				



Kokkos Tools Static Analysis



- clang-tidy passes for Kokkos semantics
- Under active development, requests welcome
- IDE integration

```
Kokkos::parallel for(
   TPolicy, KOKKOS LAMBDA(TeamMember const& t) {
     int a = 0;
     Kokkos::parallel for(TTR(t, 1), [8](int i) { Lambda capture modifies reference capture variable 'a' that is a local
       a += 1:
       cv() += 1:
Kokkos::parallel_for(
   TPolicy, KOKKOS_LAMBDA(TeamMember const& t) {
                  = 0:
     auto lambda = [5](int i) { Lambda capture modifies reference capture variable 'b' that is a local
       b += 1:
       cv() += 1;
      Kokkos::parallel_for(TTR(t, 1), lambda);
```

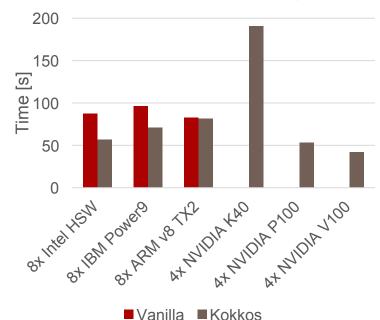


Questions: Stan Moore



- Widely used Molecular Dynamics
 Simulations package
- Focused on Material Physics
- Over 500 physics modules
- Kokkos covers growing subset of those
- REAX is an important but very complex potential
 - USER-REAXC (Vanilla) more than 10,000 LOC
 - Kokkos version ~6,000 LOC
 - LJ in comparison: 200LOC
 - Used for shock simulations

Architecture Comparison Example in.reaxc.tatb / 196k atoms / 100 steps

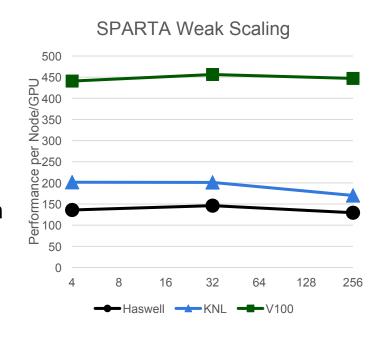




Sparta: Production Simulation at Scale



- Stochastic PArallel Rarefied-gas Timeaccurate Analyzer
- A direct simulation Monte Carlo code
- Developers: Steve Plimpton, Stan Moore, Michael Gallis
- Only code to have run on all of Trinity
 - 3 Trillion particle simulation using both HSW and KNL partition in a single MPI run (~20k nodes, ~1M cores)
- Benchmarked on 16k GPUs on Sierra
 - Production runs now at 5k GPUs
- Co-Designed Kokkos::ScatterView



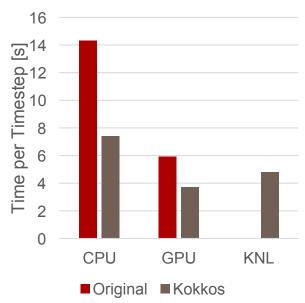




- System wide many task framework from University of Utah led by Martin Berzins
- Multiple applications for combustion/radiation simulation
- Structured AMR Mesh calculations
- Prior code existed for CPUs and GPUs
- Kokkos unifies implementation
- Improved performance due to constraints in Kokkos which encourage better coding practices

Questions: Dan Sunderland

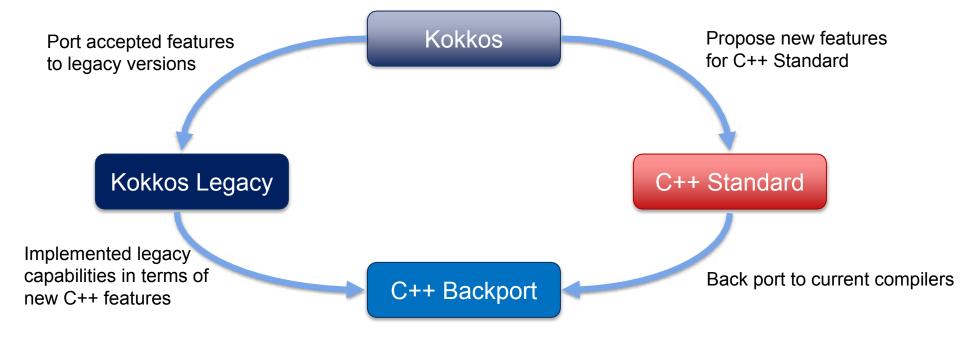
Reverse Monte Carlo Ray Tracing 64^{^3} cells





Kokkos - C++ Standard integration cycle 🛅 Sandia Laboratories







C++ Features in the Works



- First success: atomic_ref<T> in C++20
 - Provides atomics with all capabilities of atomics in Kokkos
 - atomic_ref(a[i])+=5.0; instead of atomic_add(&a[i],5.0);
- Next thing: Kokkos::View => std::mdspan
 - Provides customization points which allow all things we can do with Kokkos::View
 - Better design of internals though! => Easier to write custom layouts.
 - Also: arbitrary rank (until compiler crashes) and mixed compile/runtime ranks
 - We hope will land early in the cycle for C++23 (i.e. early in 2020)
 - Production reference implementation: https://github.com/kokkos/mdspan
- Also C++23: Executors and Basic Linear Algebra: https://github.com/kokkos/stdblas





Tracking New Capabilities: Graphs



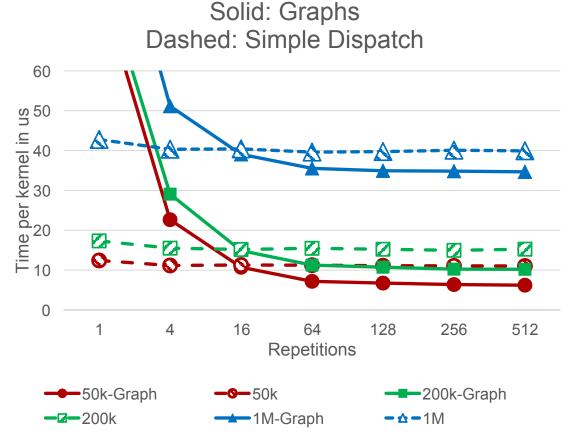
- Build static graphs of kernels
 - Can use CUDAGraphs as backend
 - Allows repeated dispatch
- Helps with Latency Limited codes
 - Cuts down on launch latency
 - Can leverage streams to overlap work
 - Infers overlapping from dependencies
- Prototype release part of Kokkos 3.3

```
const auto graph = Kokkos::Experimental::create graph(
  [=](auto root) {
  auto f1 = root.then parallel for(
    Kokkos::RangePolicy<>(0, 1), KOKKOS_LAMBDA(long) {...});
  auto f2a = f1.then parallel for(
    Kokkos::RangePolicy<>(0, 1), KOKKOS LAMBDA(long) {...});
  auto f2b = f1.then_parallel_for(
    Kokkos::RangePolicy<>(0, 1), KOKKOS_LAMBDA(long) {...});
  when_all(f2a, f2b).then_parallel_reduce(
    Kokkos::RangePolicy<>(0, 1), KOKKOS LAMBDA(long) {...}
    result);
});
while(result()>threshold {
  graph.submit();
  graph.get_execution_space().fence();
```



Benchmark the Example





Can reuse graph:

- In solver iterations
- Between solves if matrix structure unchanged
- >100 reuses could be realistic

Throughput Improvement:

- 50K 78%
- 200k 49%
- 1M 15%

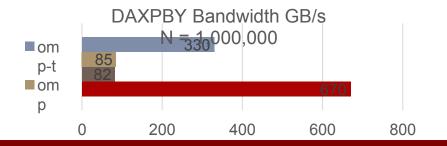
Next: look at reducing graph creation time

OpenMPTarget Status

- Most capabilities are now working
 - Until earlier in 2020 limited by compiler bugs
- Using primarily main line clang/llvm
 - Are also working with Intel and NVIDIA
 - Started working with AMD and HPE
- Next phase: concentrating on performance
 - C++ performance very fragile
 - We are ramping up collaboration with compiler engineers

Vector Add Performance Illustration

- Simple problem, should clearly be bandwidth limited
- Using clang/llvm 11, CUDA 10.1, NVIDIA V100
- Kokkos/CUDA (kk-c), Kokkos/OMPT (kk-o), Native OMPT (omp), Native OMPT with temporaries (omp-t)

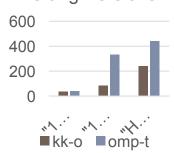


OpenMP Vector Add

```
struct Foo {
  int N;
  double *x, *y, *z;
  void axpby() {
    // Need temporaries here for 4x performance gain
    int N_ = N;
    double *xp = x, *yp = y, *zp = z;
    #pragma omp target teams distribute parallel for \
        simd is_device_ptr(xp,yp,zp) data map(to: N_)
    for(int i=0; i<N_; i++) {
        zp[i] = xp[i] + yp[i];
    }
};</pre>
```

Kokkos Vector

DAXPBY GB/s Clang Versions



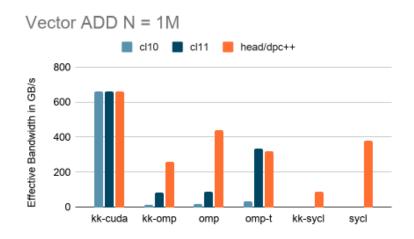
10.0: released March 2020 11.0: released October 2020

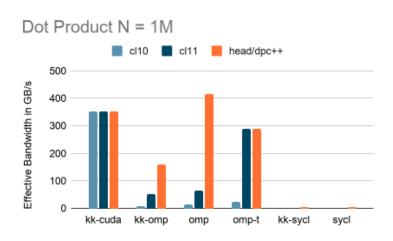
Takeaway: Performance is still very fragile!

A more comprehensive Frontend/Compiler comparison



- Comparing simple vector add and dot product
 - Also implemented straight forward native implementation
 - No hoops jumped through to optimize
 - 1M length, not huge, but also not trivial, i.e. latency impact expected but not dominant?
 - If purely bandwidth bound this would be 24us for axpby@1TB/s and 16us for dot
 - clxx denotes clang/llvm version





Sake: Kokkos Kernels

- What parts of your code are you porting to the accelerator, and what fraction of overall performance does this code account for in a realistic problem?
 - All of Kokkos Kernels is ported to accelerators, linear solvers can account for a large portion (up to 50%)
 of the overall performance of an application
- What accelerator programming environments were used? What is the long-term performance portability plan for exascale machines with different types of GPUs?
 - Kokkos Kernels relies on the Kokkos library to provide basic data structure and parallel execution policies. Currently all GPU architectures are supported through backends of Kokkos (Cuda, HIP, SYCL and OpenMP Target) and our algorithms are further tuned internally for performance.

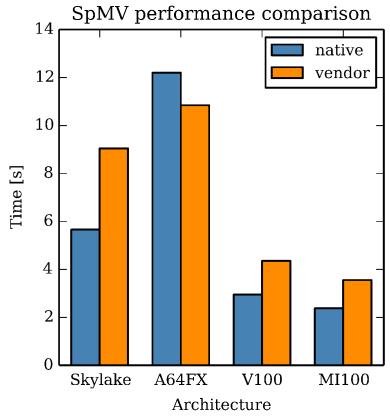
Currently the library is built and tested daily on Power9+V100 with the Kokkos Cuda backend and on Rome+MI100 with the Kokkos HIP backend. Work is ongoing to support daily testing of the OpenMP Target backend on both previously mentioned systems. Development is ongoing on JLSE systems with Kokkos SYCL backend.



Sake: Kokkos Kernels

 What single node speedup (if any) was achieved relative to the best performance on other classes of systems?

- Shown on the right is the performance of our native SpMV implementation against vendor TPLs (MKL, ArmPL, cuSPARSE and rocSPARSE).
- Our implementations strive to extract best performance on each architecture but also allow direct calls to vendor TPLs when possible or needed providing users with good baseline performance for most common linear algebra kernels.
- Note that the results in figure to the right are subject to change depending on the matrix used for comparison, here two matrices representative of finite element/difference discretization were used





Sake: Kokkos Kernels

- What are the key bottlenecks, if any, to improving on-node performance, including plans for how to address them? For example, will there be a need to explore risky, fundamentally new algorithmic approaches, different mathematical formulations, or more fine tune for specific hardware features?
 - For Nvidia GPUs the performance is currently well established and no issues are foreseen
 - For AMD GPUs further tuning of the native algorithms is needed to accommodate specificities of the architecture such as wavefront size. Additionally rocBLAS and rocSPARSE needs to be expanded.
 - For Intel GPUs more issues exist, the OpenMP Target and SYCL backends are still under development with new bugs being reported to Kokkos. Some kernels are being refactored to favor reduction on single value instead of reducing on array of values.
 - New batched algorithms for dense and sparse linear algebra are being developed for specific applications need.



Sake: Kokkos Kernels – recent work

New algorithms

- MIS-2 kernels optimized and fully integrated with Trilinos/MueLu (multigrid package)
- Batched sparse linear algebra and solvers (SpMV, CG and GMRES)
- BsrMatrix and SpMV, will impactful for ATDM applications

Library design

- New stream interface: supports GEMV and GEMM on CUDA and HIP
- Documentation publication automated at release time
- clang-format checked during CI testing
- Support for half precision

• Improvements

- Optimized batched GEMM interface and performance (+3% DRAM utilization)
- Add support for rocBLAS/rocSPARSE



Sake: Kokkos Kernels – upcoming work

Algorithms

- further support for BsrMatrix format: SpGEMM, Jacobi and Gauss-Seidel
- batched Sparse Solvers: preconditioners, performance optimization and integration with applications
- Device callable ODE solvers, potentially batched implementation too
- Improve SpTRSV and SpILUK performance on device
- Improve SpGEMM performance

Library design

- expand Stream interface to more kernels
- Re-organize library with multiple build targets (allows subset of feature to be compiled)
- Provide iterative solver interface (call from host to GPU)
- Improve SYCL and OpenMP Target support and performance

