

# PETSc Rocks

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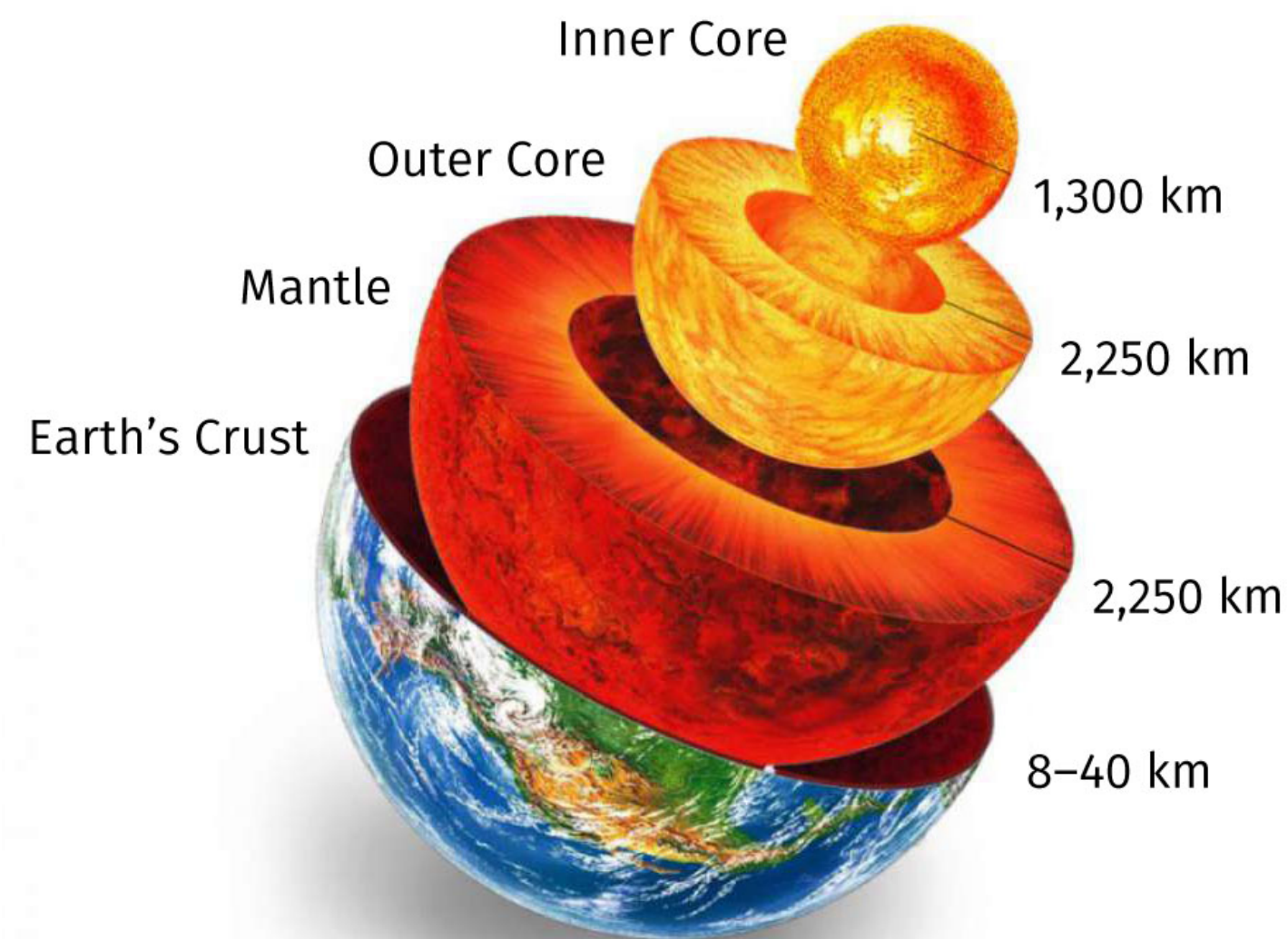
# Outline

- The Earth, observations, and rheology of rocks
- Geodynamic modeling of long-time scale processes
- pTatin3D - a PETSc framework for regional scale geodynamics
- Application software driving PETSc dev
- Summary

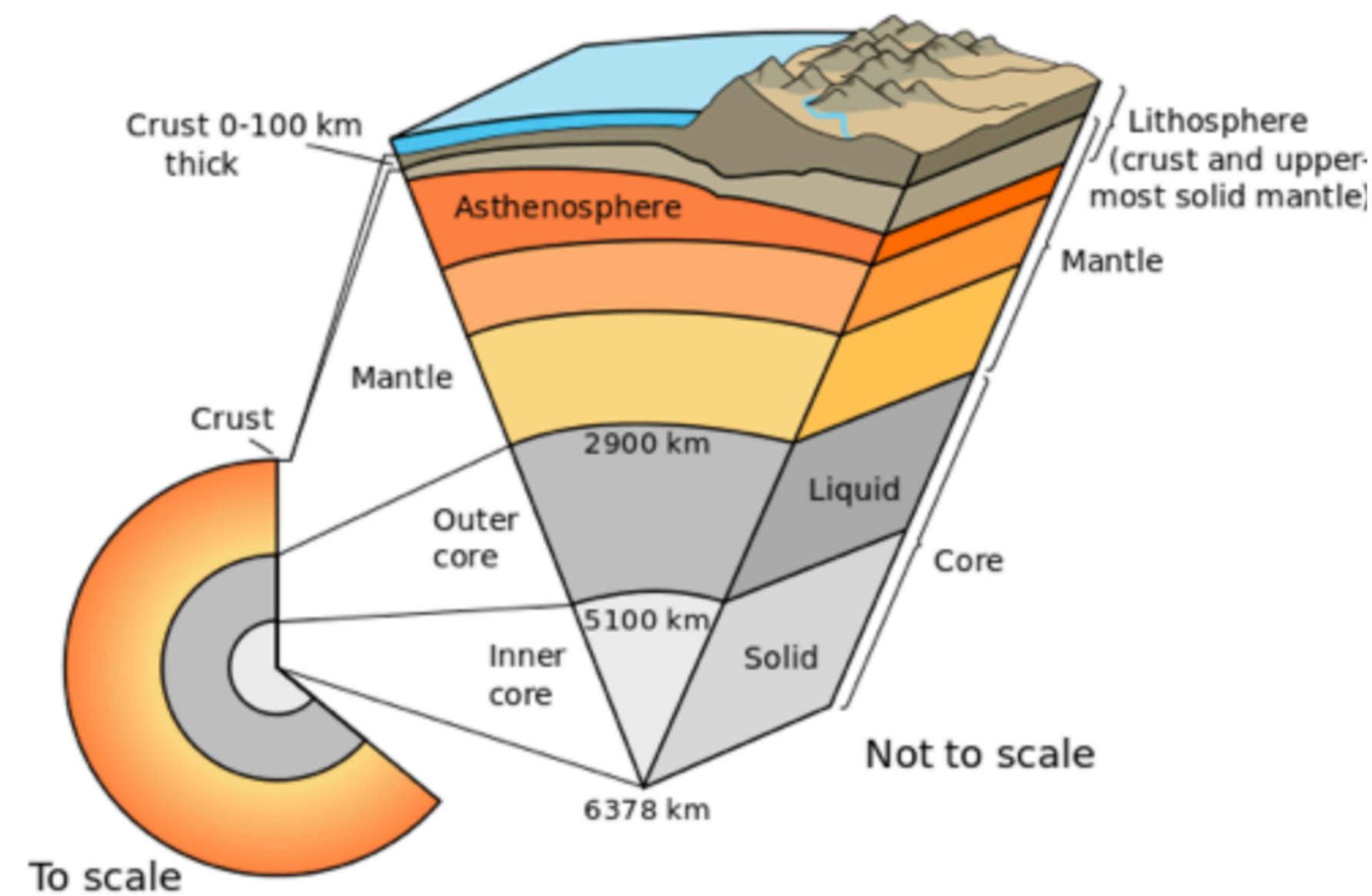


# Structure of the Earth

- The familiar onion model

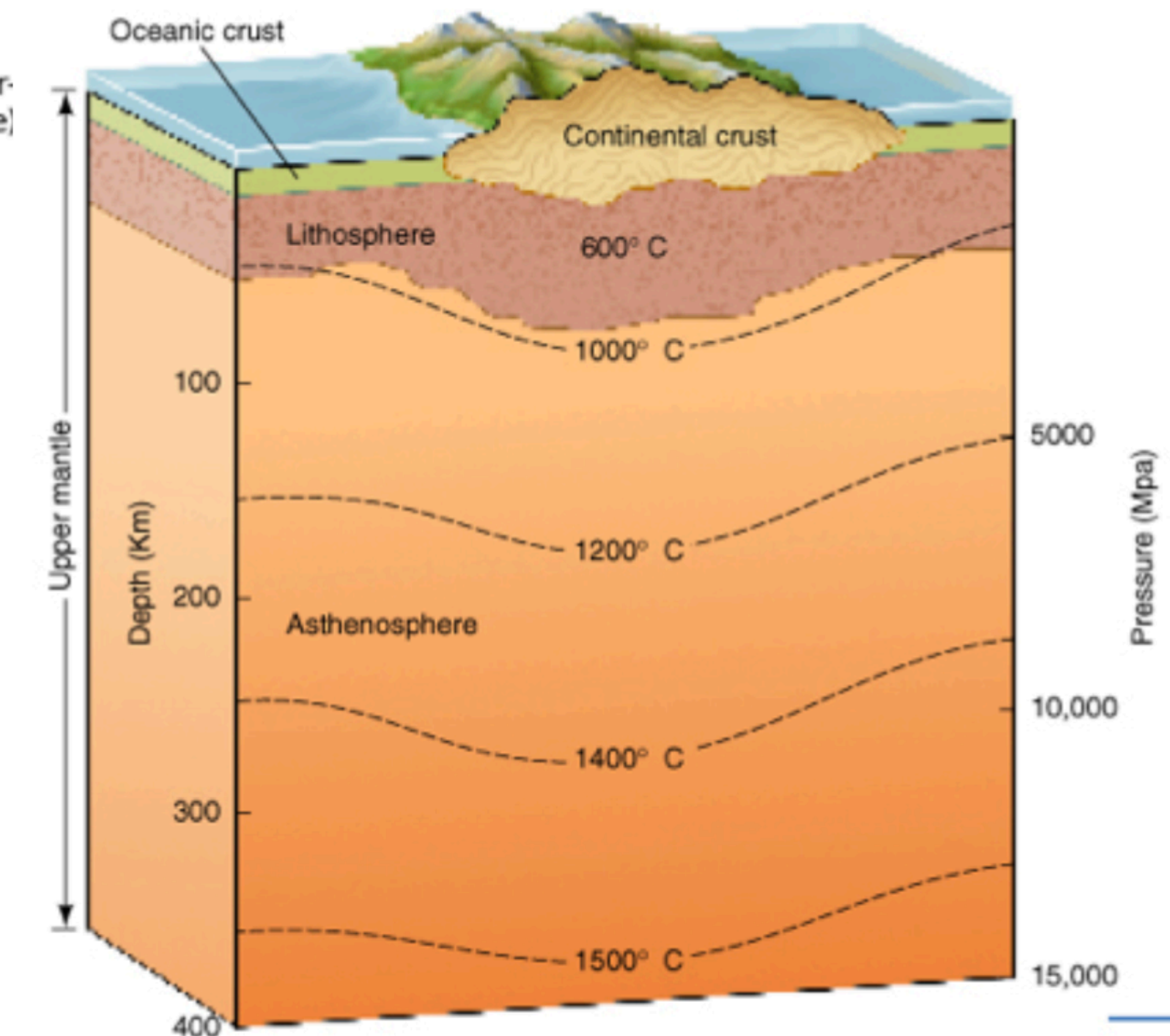


<https://www.the-dialogue.com/en/en66-how-plate-tectonics-is-connected-with-life-on-the-planet/>



<http://opengeology.org/textbook/2-plate-tectonics/>

**global scale**



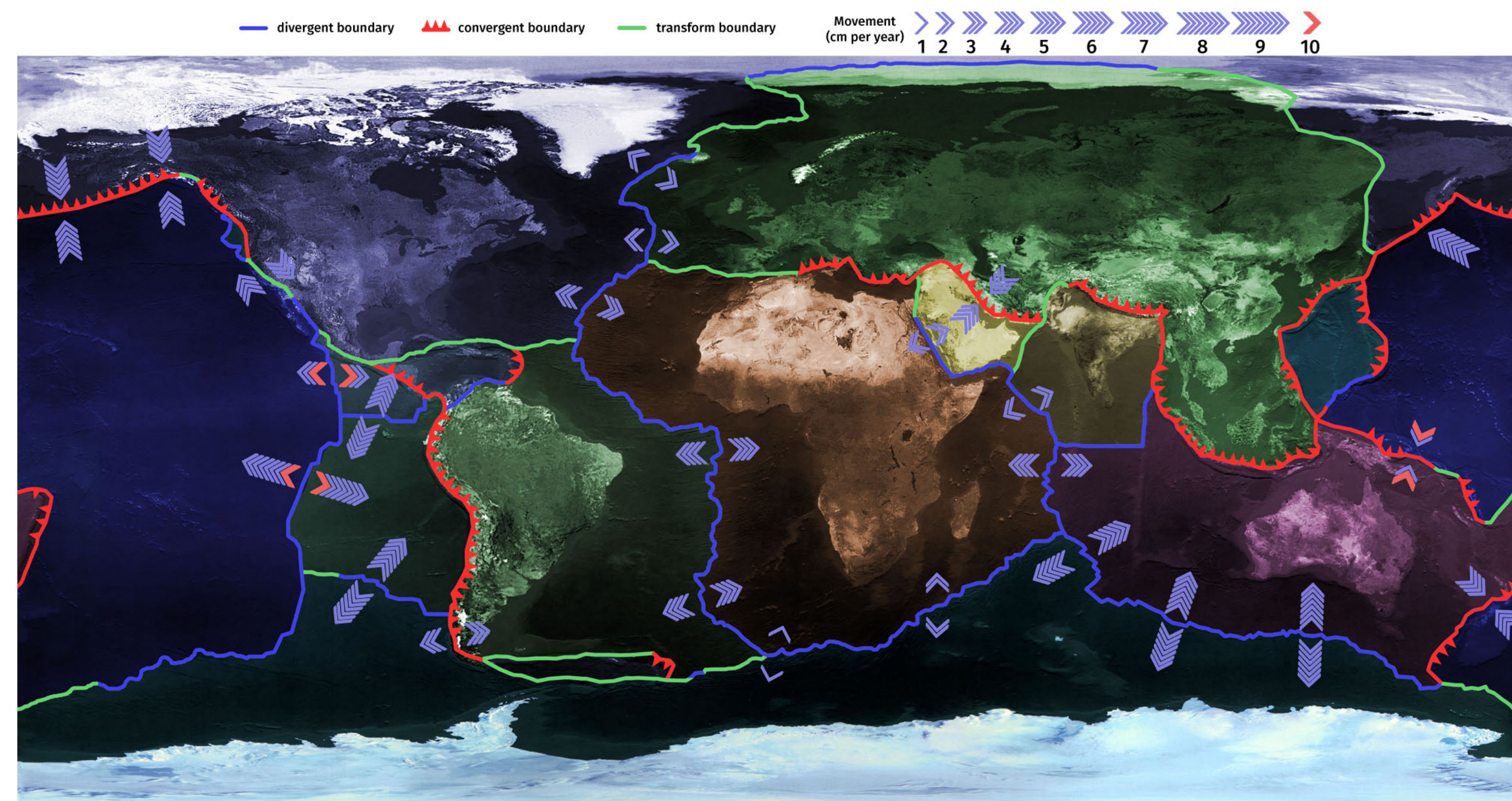
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**regional scale**



# Plate tectonics paradigm

- A set of lithospheric plates covering the entire surface of the Earth. 7 major plates represent ~95% of the surface.
- Plates are composed of a mixture of different lithospheric materials, i.e. oceanic, continental.
- Plates
  - move (translate, rotate);
  - deform (primarily along their boundaries);
  - interact along their boundaries. Interactions depend on the boundary segment type.
- The entire system is dynamic and time dependent.
- The age of the tectonic style we observe today is highly debated, estimates range from 1B to 4B years old.

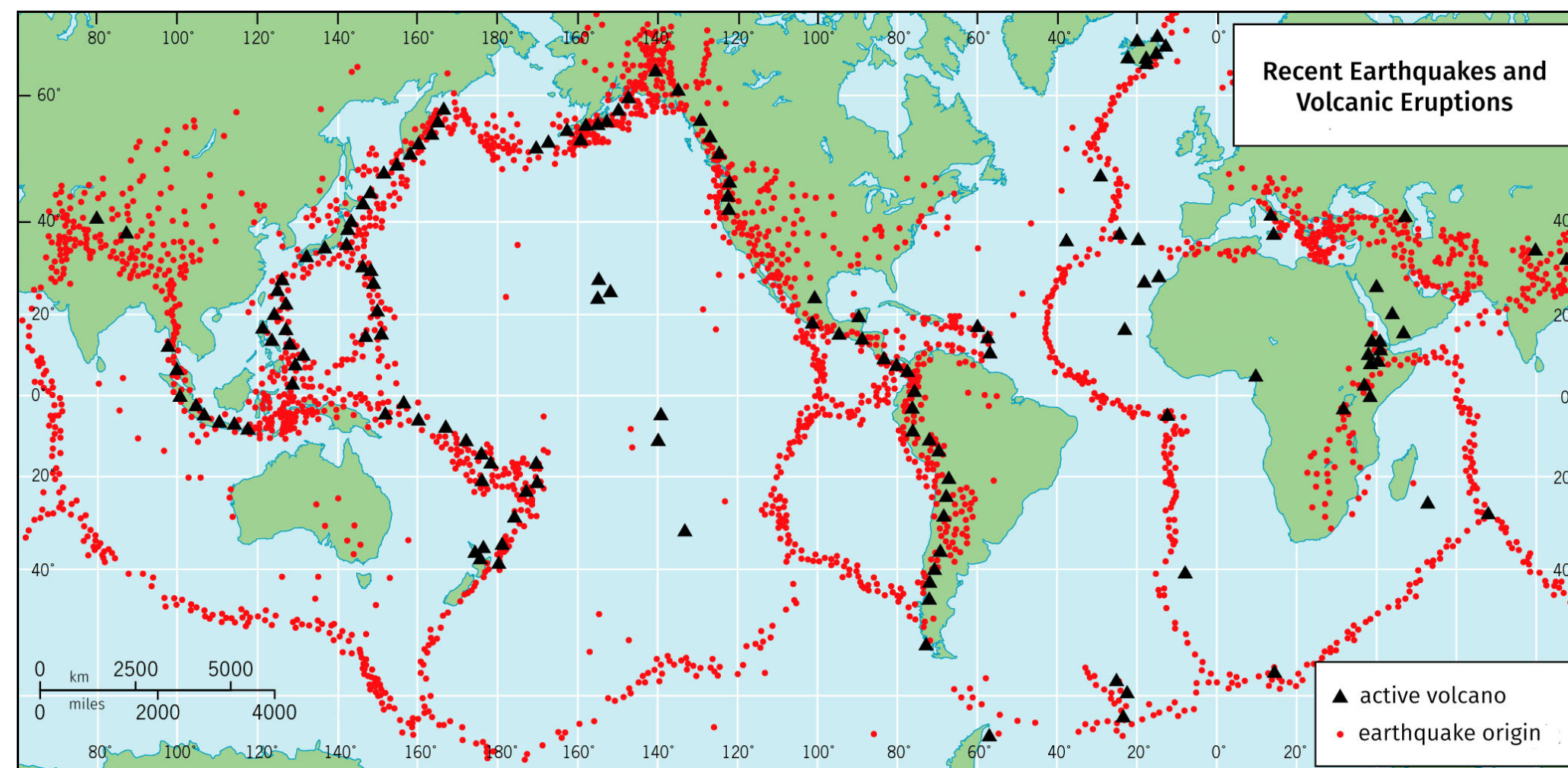


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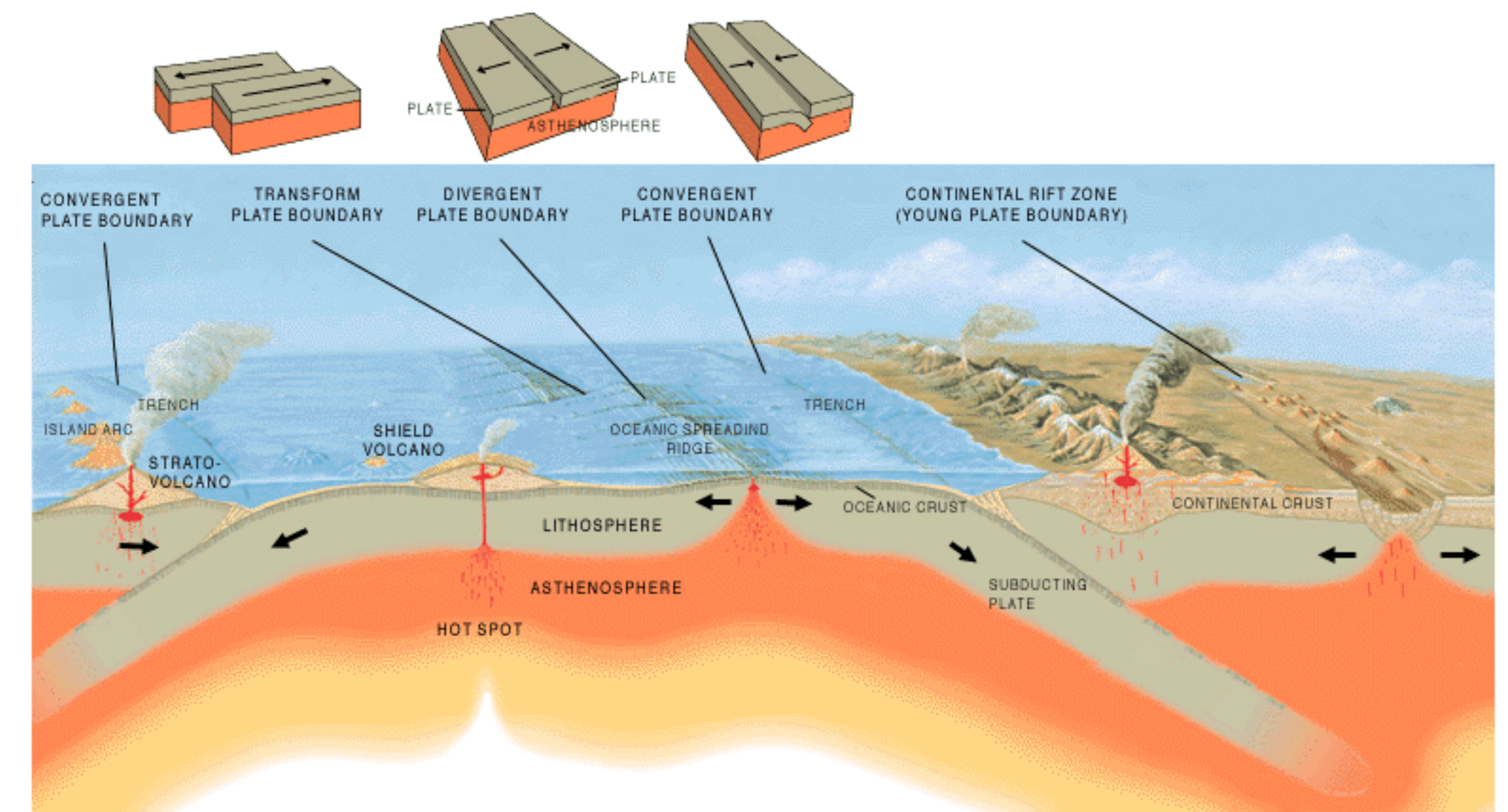


# Earthquakes occur at plate boundaries

- Earthquakes (EQs) mainly concentrated along plate boundaries
- Other EQ related hazards include tsunamis



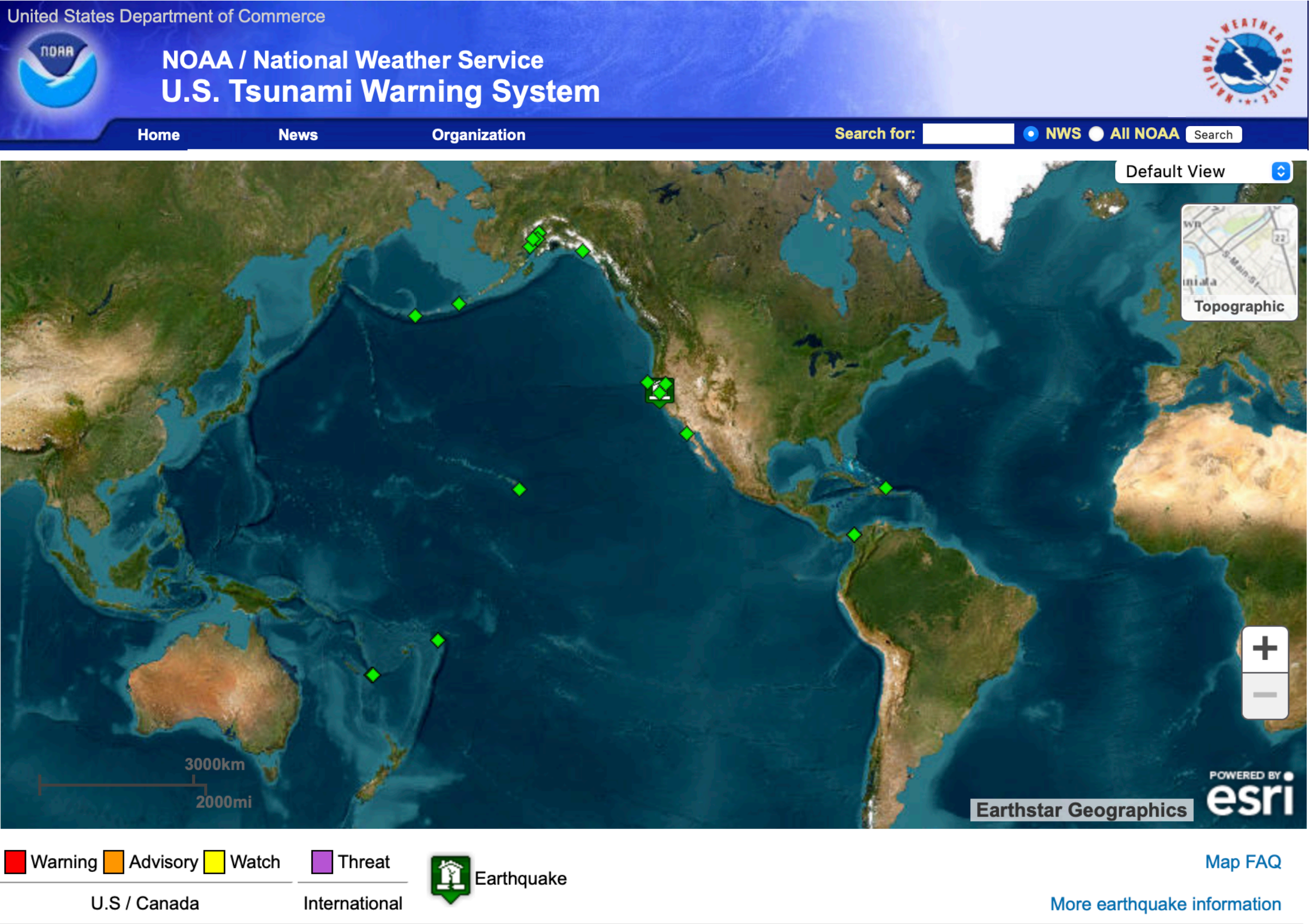
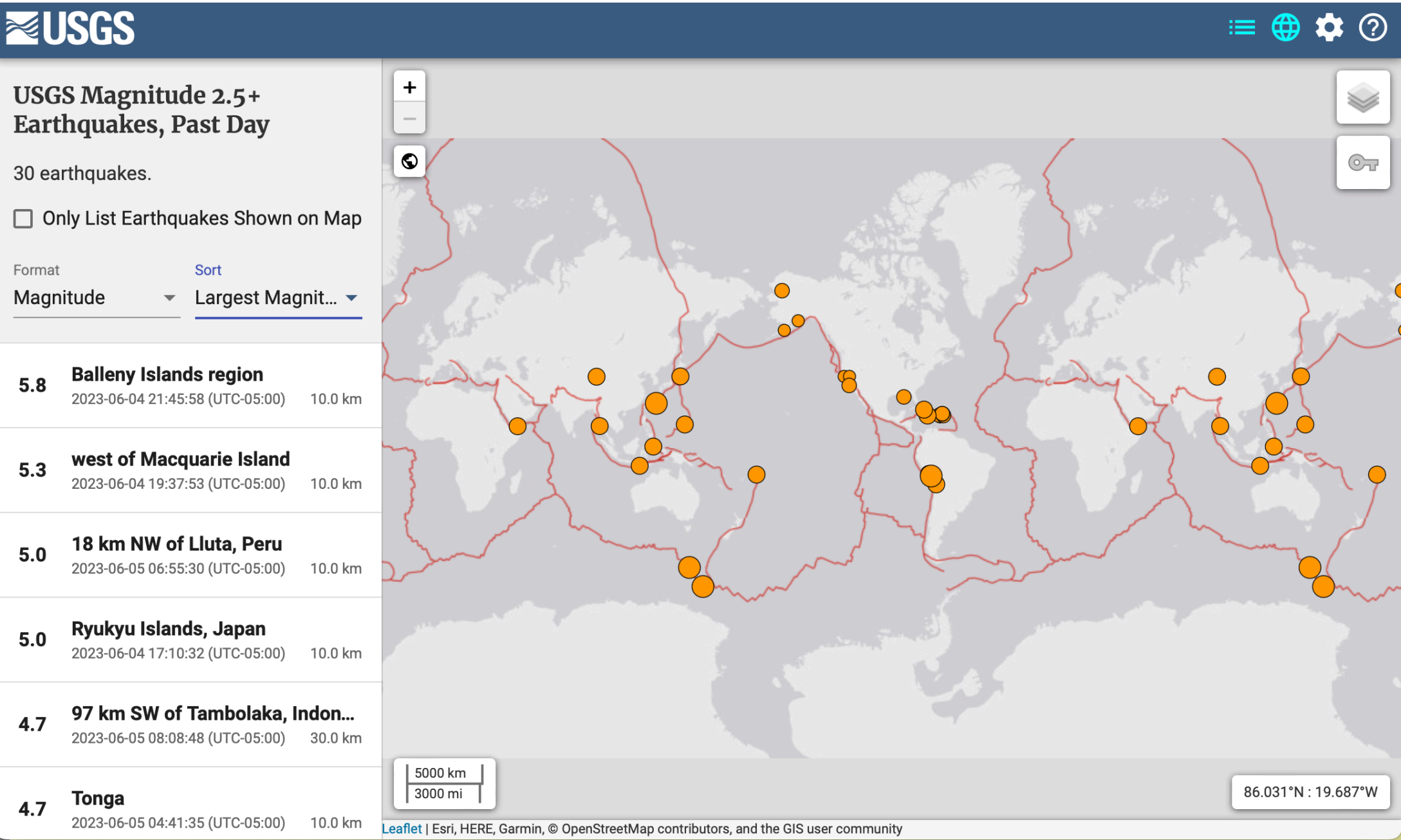
<https://www.the-dialogue.com/en/en66-how-plate-tectonics-is-connected-with-life-on-the-planet/>



<https://www.universetoday.com/43822/subduction-zone/>



# Seismic events happen all the time



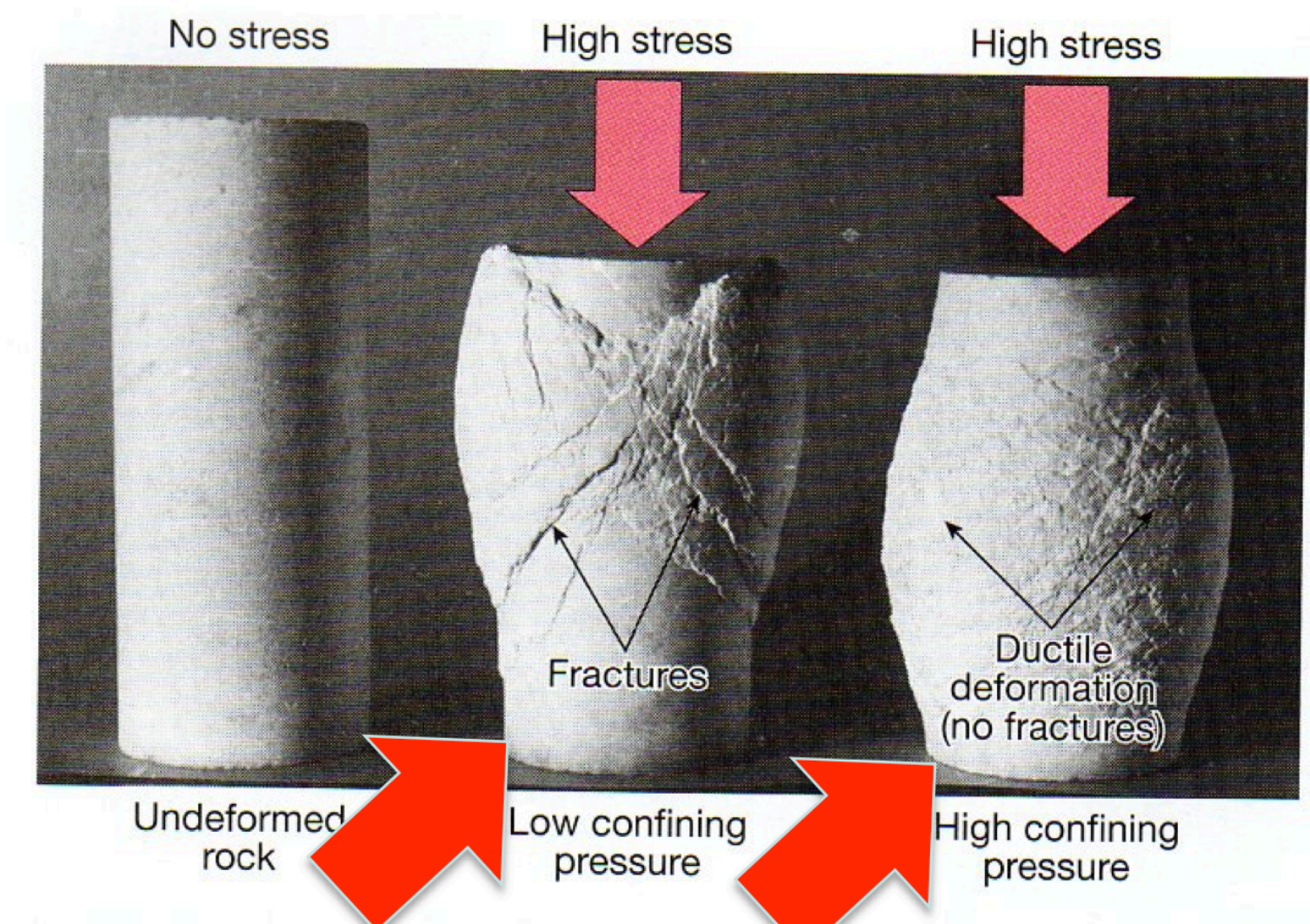
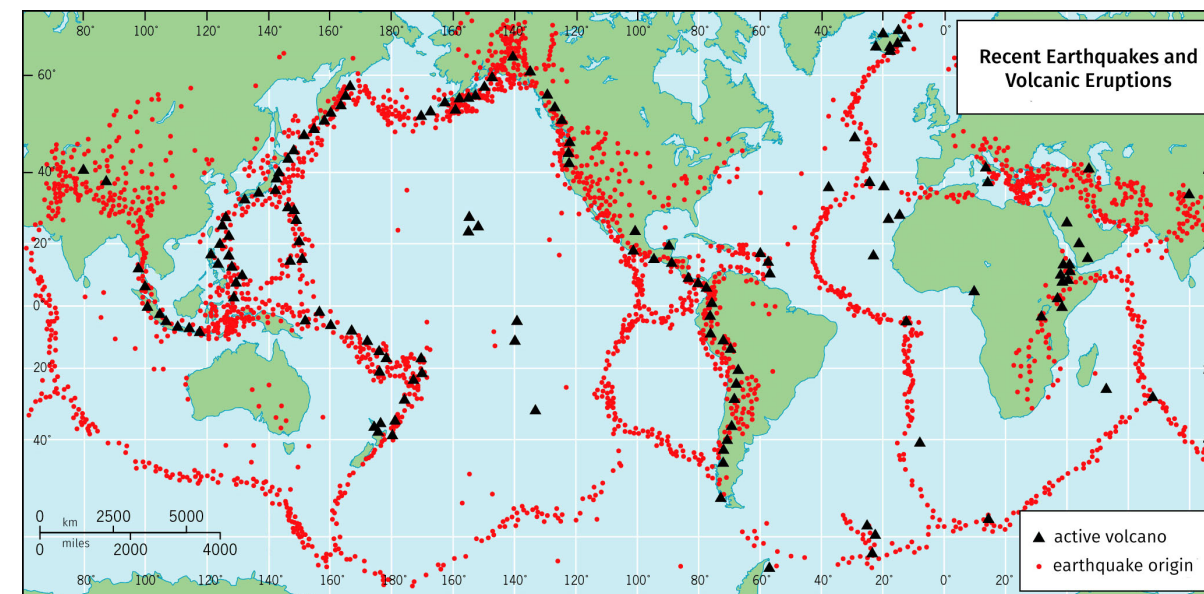
Previous 40 Tsunami Messages

Issued *	Origin Time *	Mag ⇅	Depth ⇅	Lat ⇅	Lon ⇅	Location ⇅	Messages ⇅	Additional Resources **
06-03-2023 12:06:19	06-03-2023 12:01:21	4.3	1 Mi.	38.7° N	122.7° W	65 MILES W OF SACRAMENTO, CALIFORNIA	AK/BC/US West Coast Informational #1	Select Resource
05-27-2023 16:53:51	05-27-2023 16:49:22	4.4	85 Mi.	60.3° N	152.9° W	70 MILES NW OF HOMER, ALASKA	AK/BC/US West Coast Informational #1	Select Resource
05-26-2023 02:20:50	05-26-2023 02:17:59	4.1	26 Mi.	61.7° N	150.9° W	50 MILES SW OF TALKEETNA, ALASKA	AK/BC/US West Coast Informational #1	Select Resource
05-25-2023 12:59:06	05-25-2023 12:54:33	4	7 Mi.	59.8° N	140.5° W	30 MILES NW OF YAKUTAT, ALASKA	AK/BC/US West Coast Informational #1	Select Resource



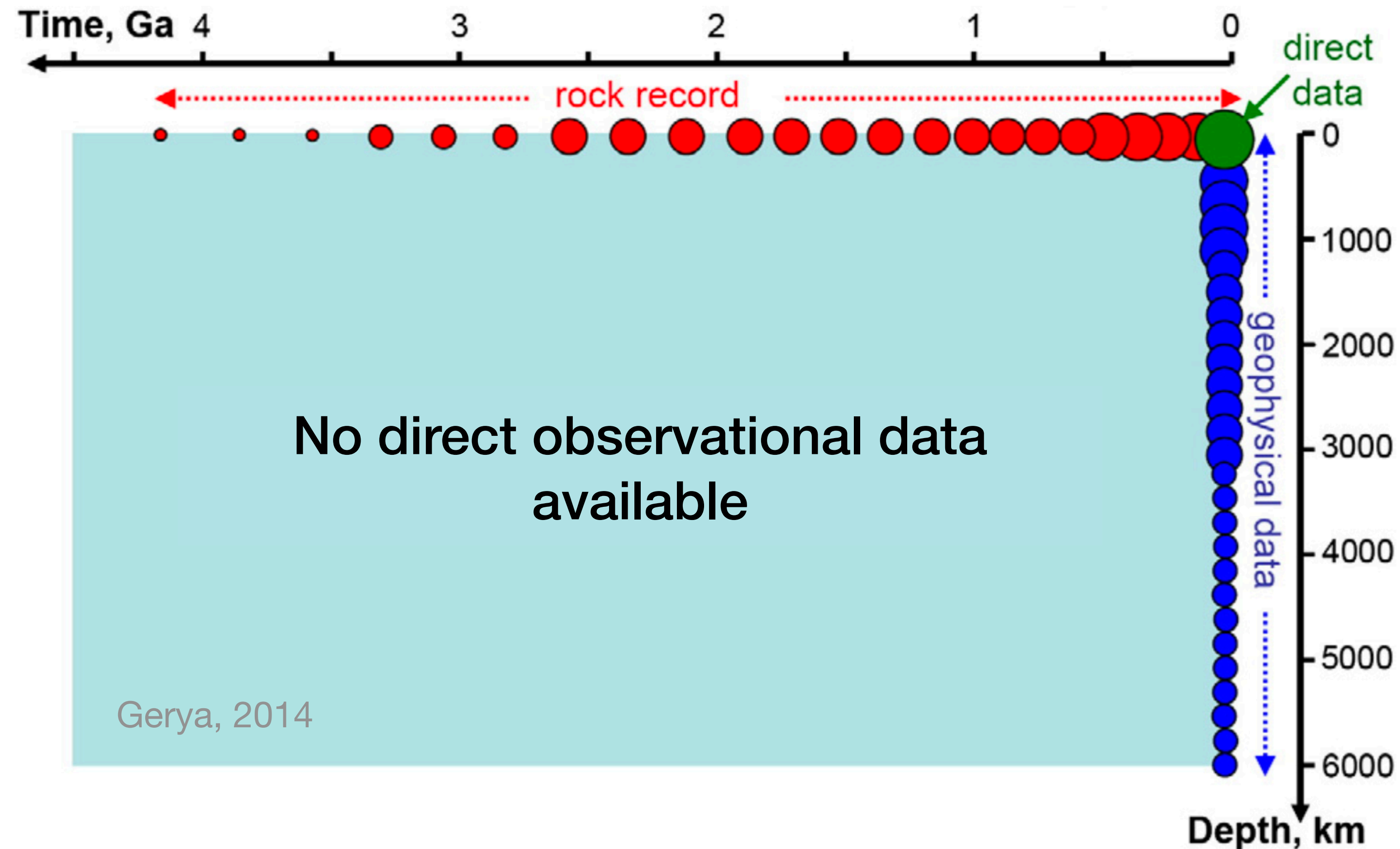
# Rock rheology

- Ductile and brittle
- Temperature dependent
- Strain-rate dependent
- Pressure dependent
- Path dependent
- Instability of rocks resulting from shear fracture, or unstable sliding at high pressure is the main cause of shallow source great earthquakes



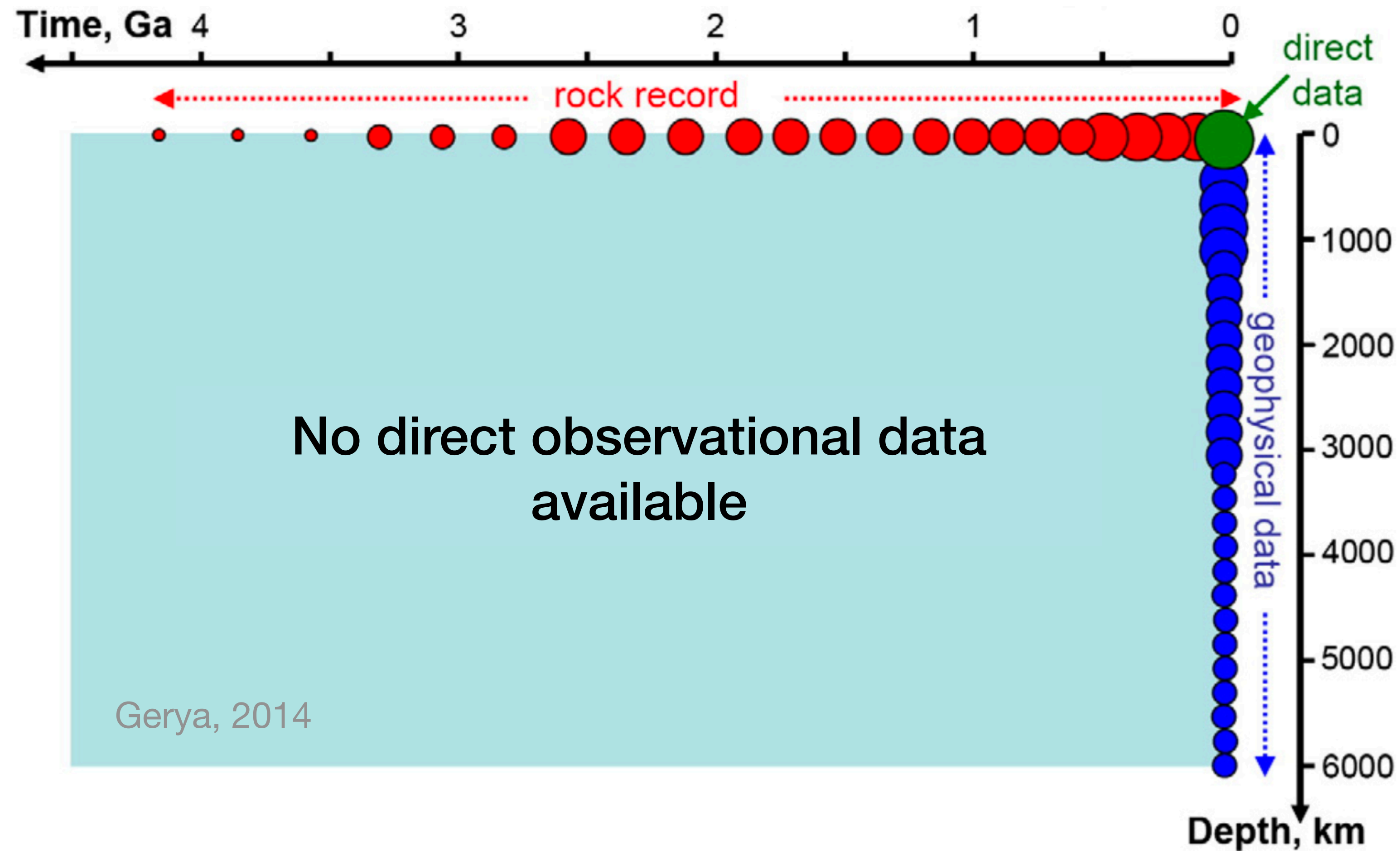


# Locality of observational constraints



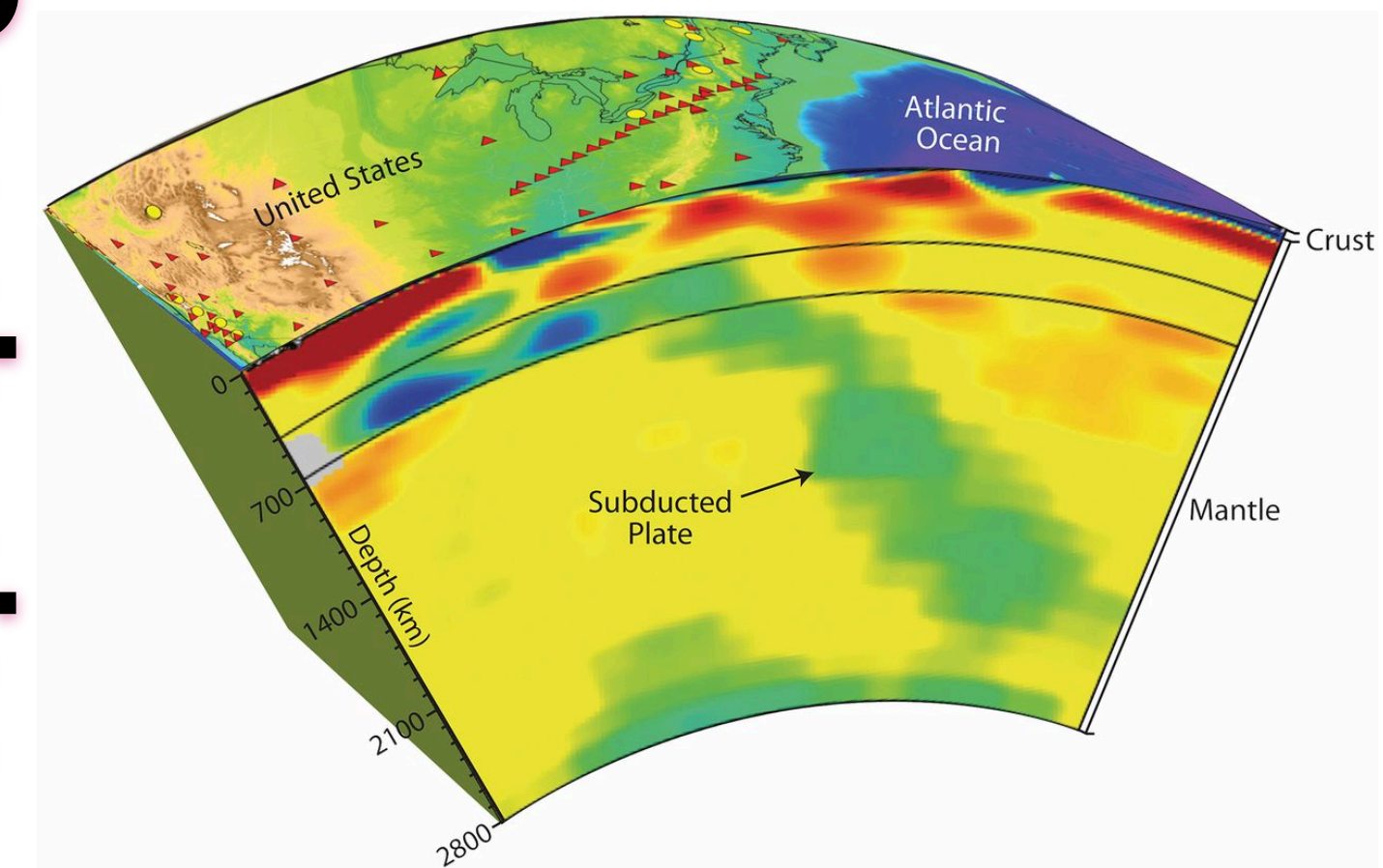


# Geology



Gerya, 2014

# Geophysics



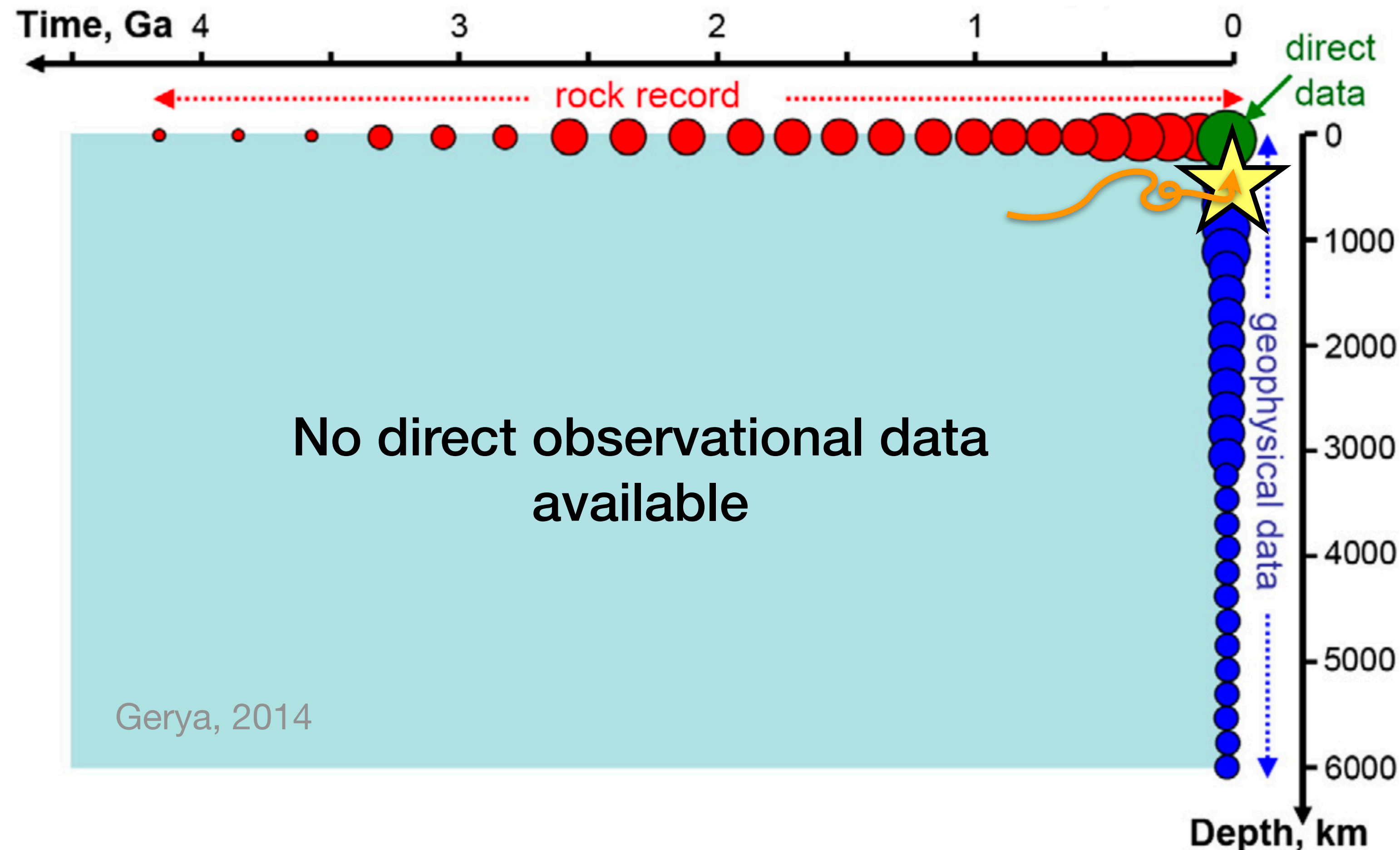
<https://www.pnas.org/doi/10.1073/pnas.1909777116>



# Geology

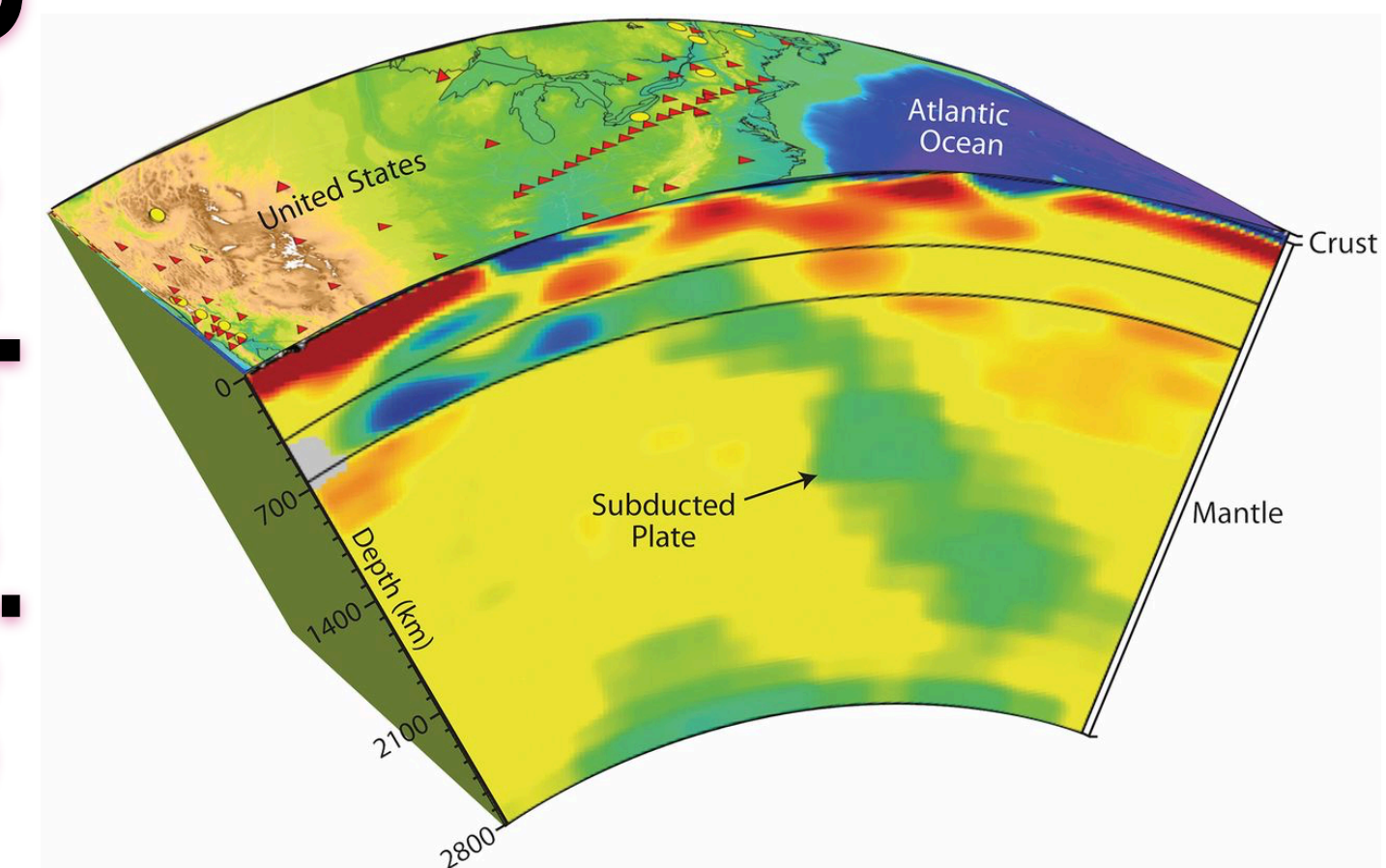


- Physics-based hazard assessment is the way forward



Gerya, 2014

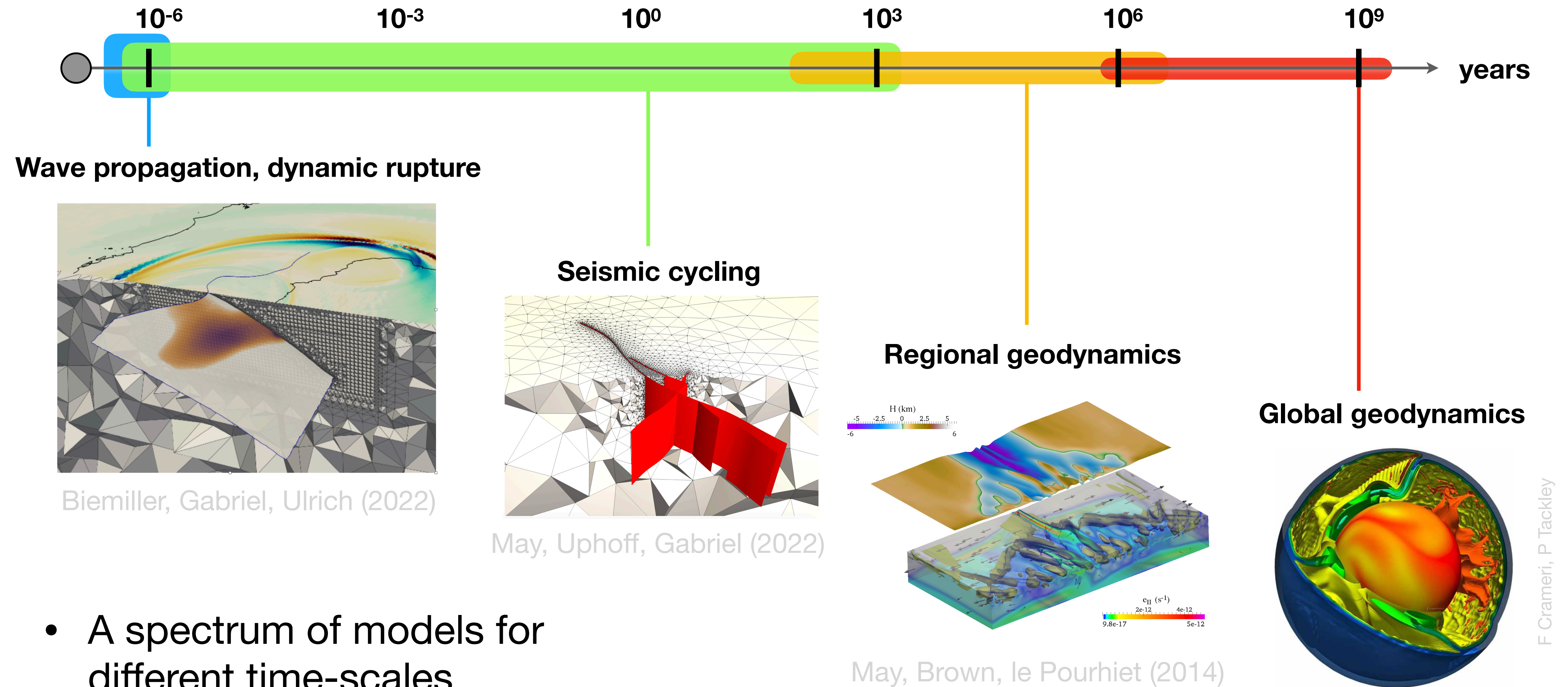
# Geophysics



<https://www.pnas.org/doi/10.1073/pnas.1909777116>



# Wide range of important time-scales



# Modelling long-term dynamics

- Incompressible viscous flow
- Highly non-linear constitutive law
- Large deformation
- Large strain
- History dependent material behaviour
- Thermo-mechanical coupling
- Free-surface evolution
- 3D space + time

$$\frac{\partial \sigma_{ij}}{\partial x_j} = \rho(T)g_i$$

$$\frac{\partial V_i}{\partial x_i} = 0$$

$$\rho C_p \frac{DT}{Dt} = \frac{\partial}{\partial x_i} \left( k \frac{\partial T}{\partial x_i} \right) + \rho H$$

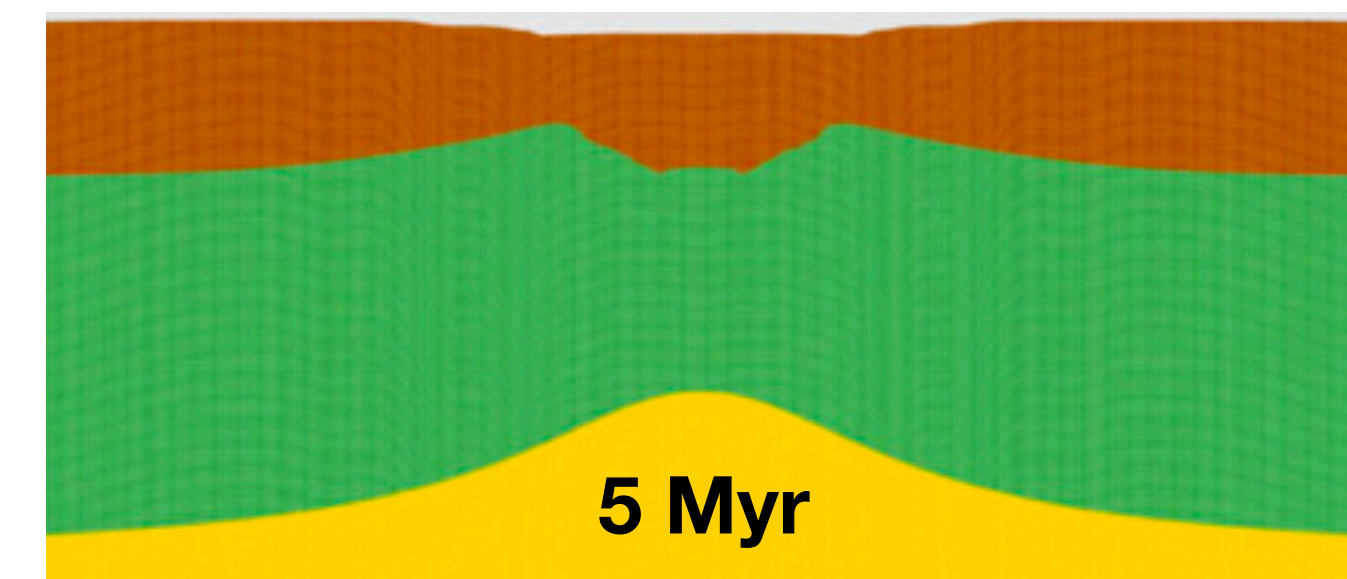
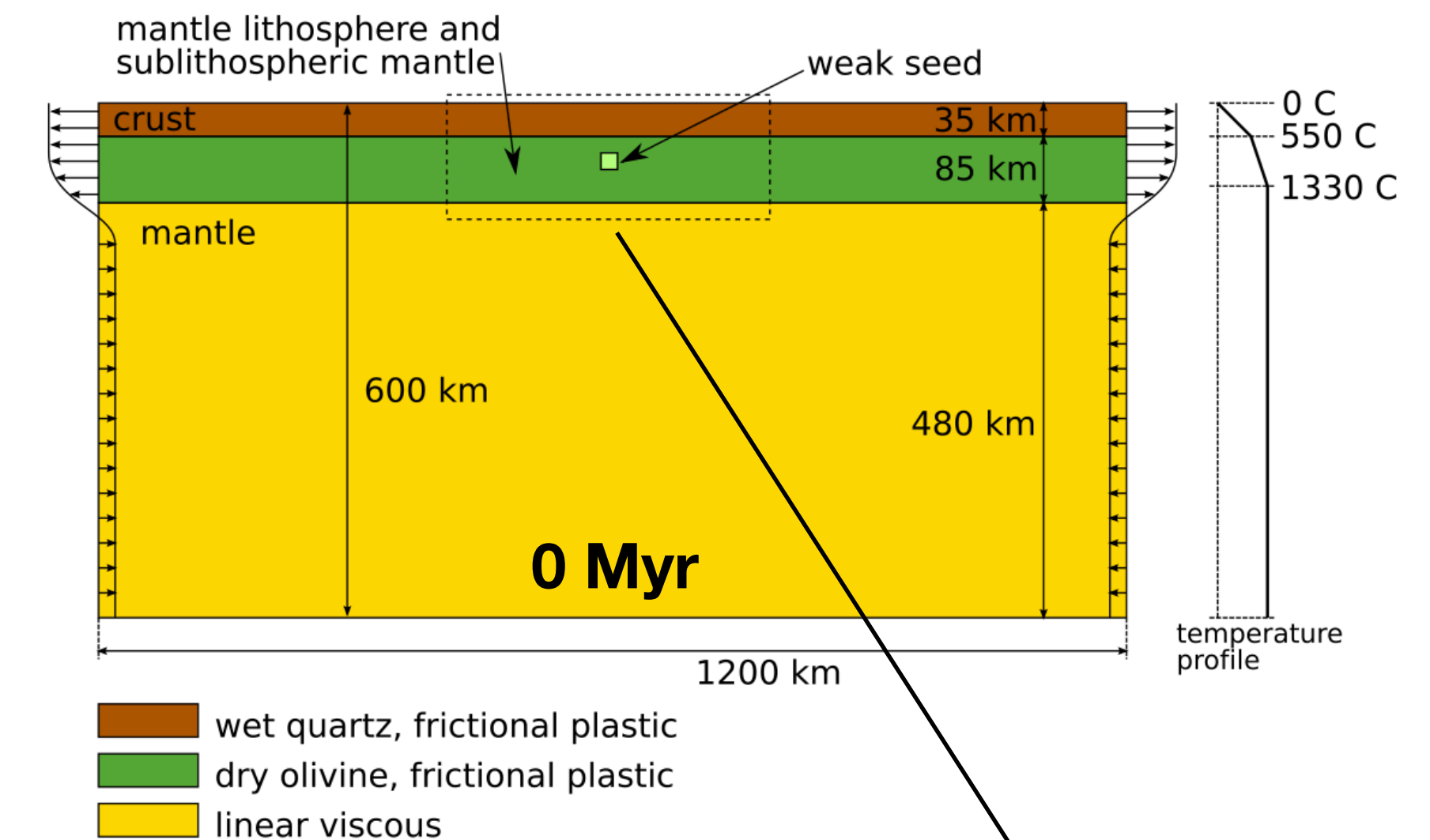
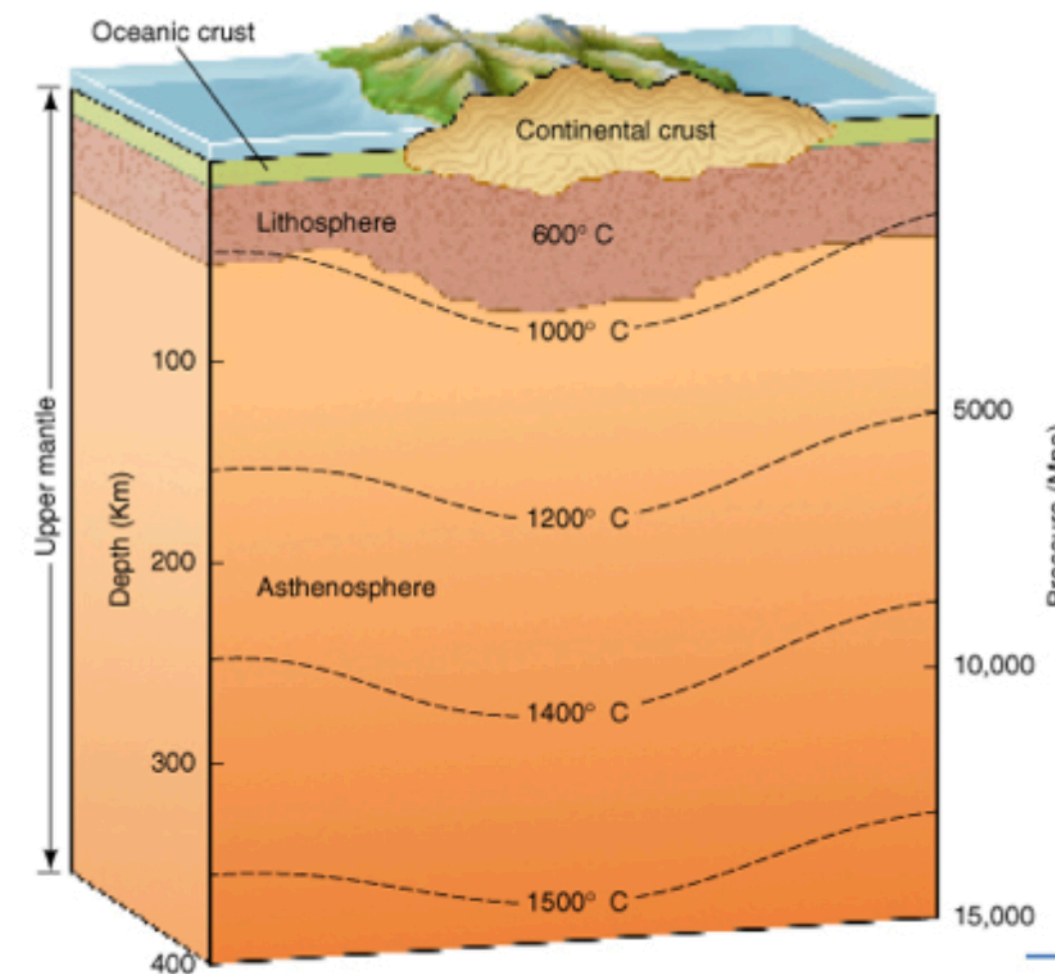
$$D_{ij} = D_{ij}^e + D_{ij}^v = \frac{\nabla \tau_{ij}}{2\mu} + \frac{\tau_{ij}}{2\eta}$$

$$|\tau| < \tau_{\text{yield}} = \tan \varphi P + C$$



# Modelling long-term dynamics

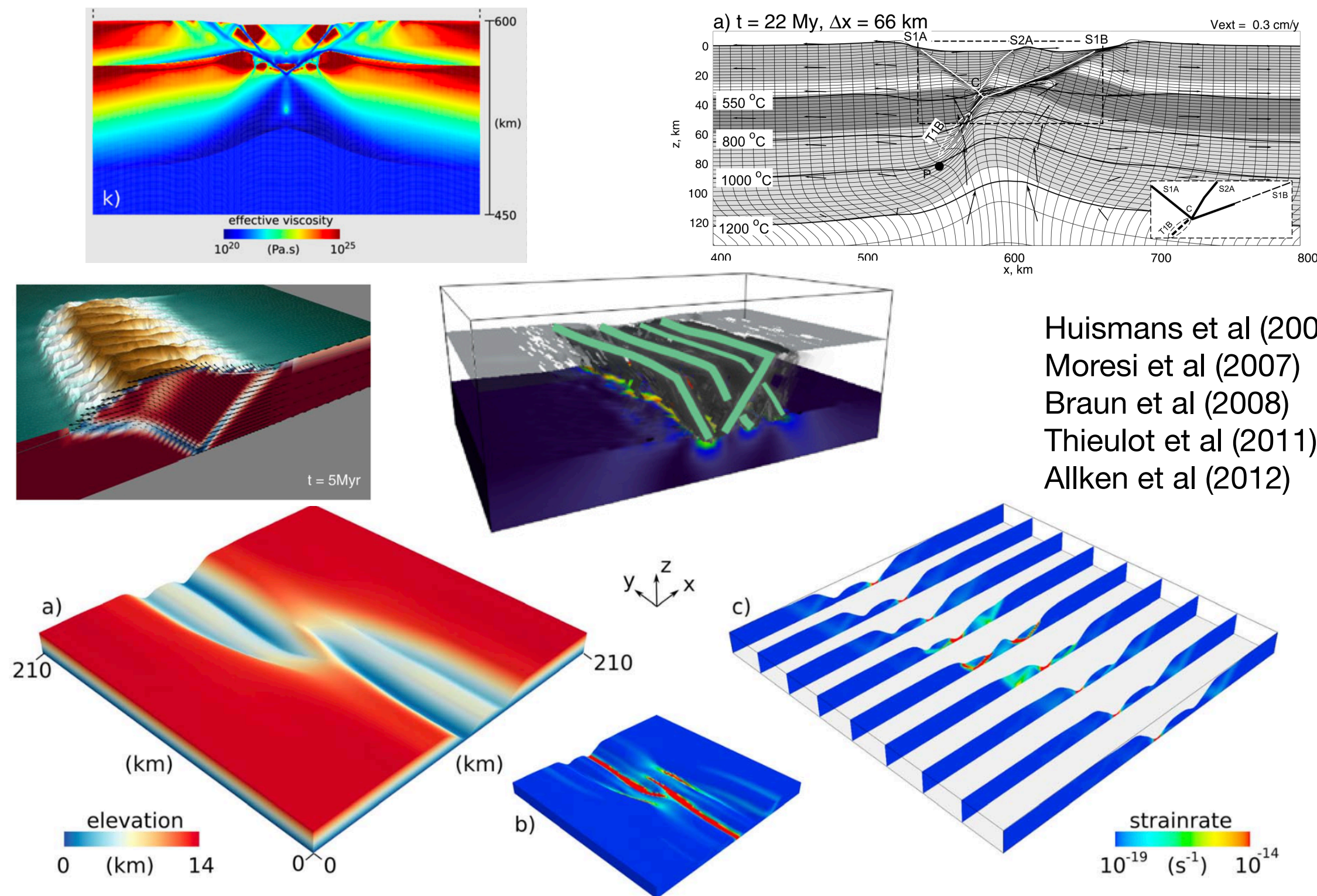
- **Large deformation**
- **Large strain**
- **History dependent material behaviour**
  - Use material points —> Lagrangian particles
  - Particles advected through mesh
  - Material point properties projected onto mesh



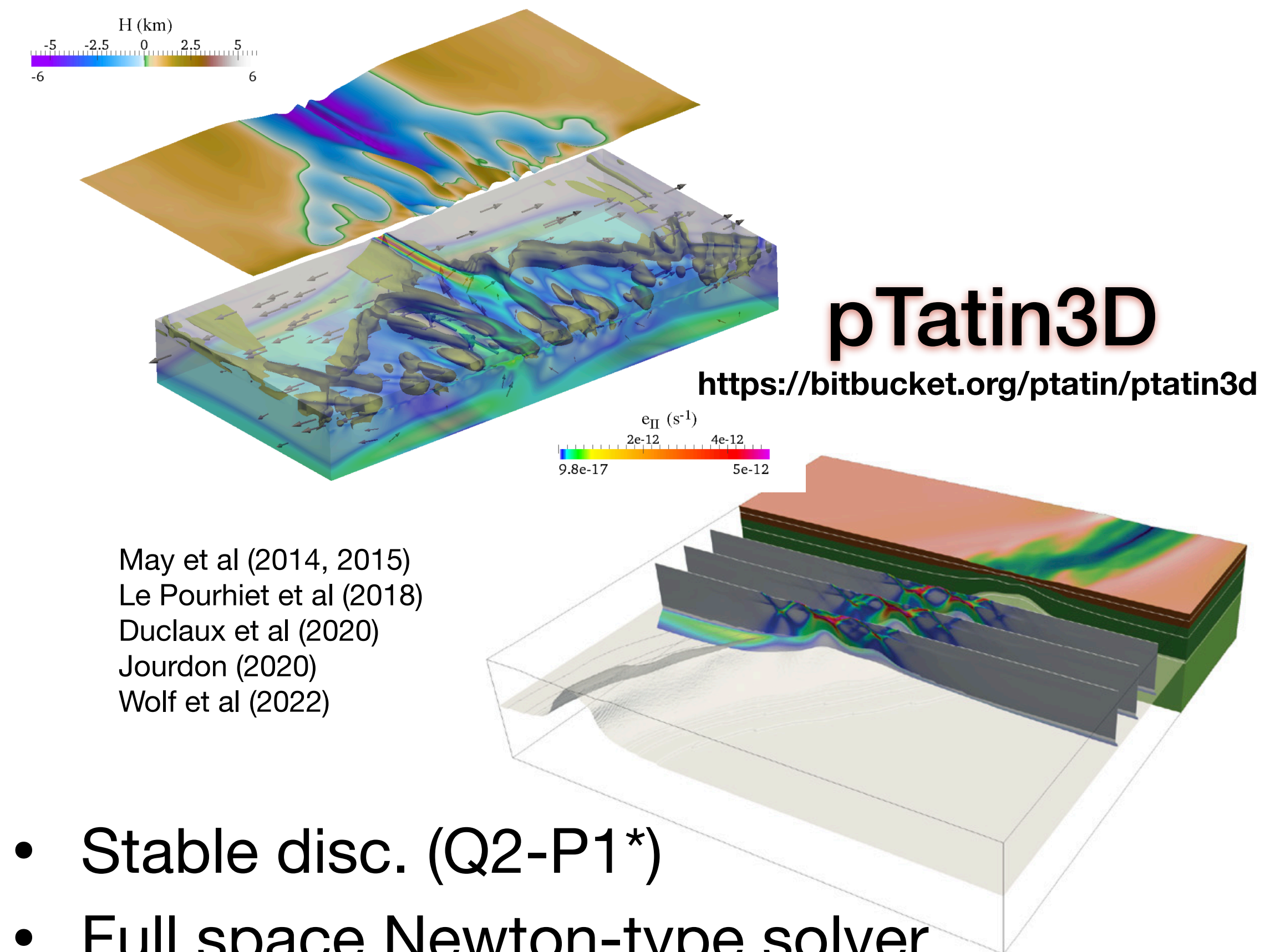
Thieulot et al (2011)



# Modelling progress over the years



Huismans et al (2003)  
Moresi et al (2007)  
Braun et al (2008)  
Thieulot et al (2011)  
Allken et al (2012)



- Non inf-sup stable disc. (Q1-P0)
- Penalty method or SCR
- Sparse direct (threaded, MPI), multigrid
- Non-scalable
- 2D high res. or 3D low res.

- Stable disc. (Q2-P1\*)
- Full space Newton-type solver
- Distributed memory
- Hybrid multigrid
- Scalable
- 3D high resolution

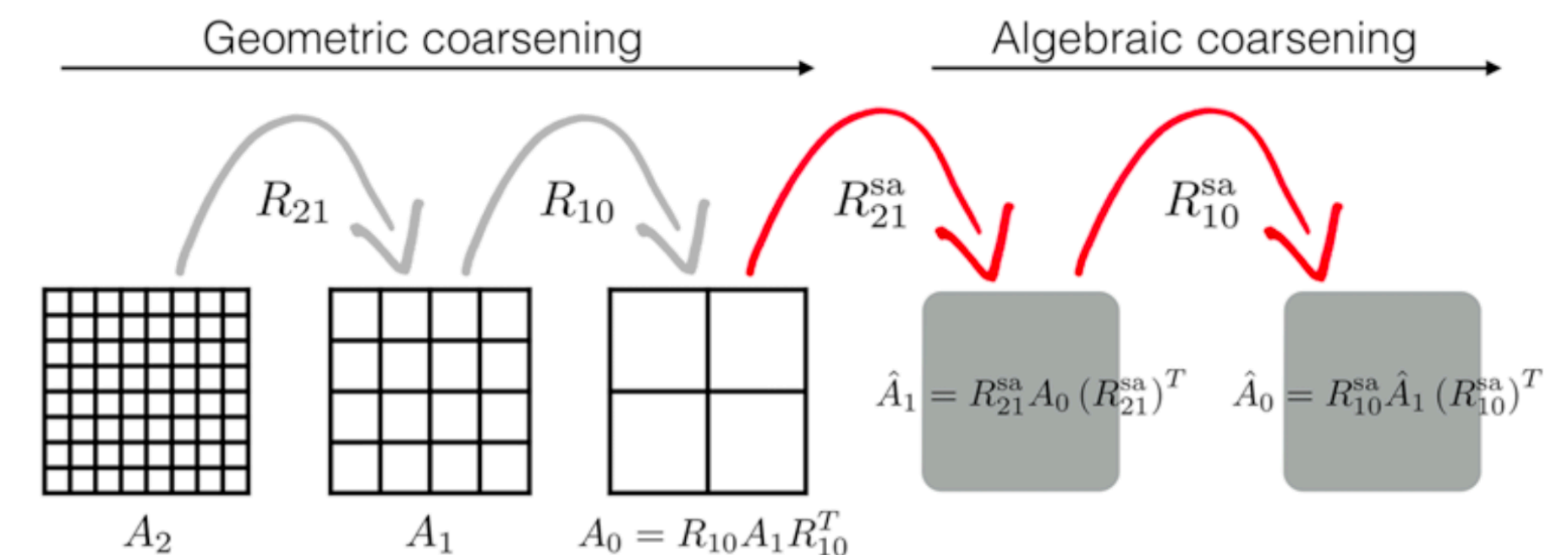


# pTatin3D | Designed for scalability and efficiency

- Structured mesh (DMDA) with Q2-P1\* discretization
- Newton Krylov framework (SNES)
- Iterate on the velocity-pressure system | MatNest, PCFieldsplit preconditioner
- Assembled (AS) or matrix-free (MF) operators
  - Naive, tensor, tensor+AVX, CUDA, ...
- Run-time multigrid customization
  - Level-wise grid coarsening
  - Selection of coarse grid operator construction and matrix type
    - e.g. re-disc MF, re-disc AS., Galerkin, MF Galerkin
  - Repartitioning of coarse grids onto fewer MPI ranks

$$\mathbf{J}\delta\mathbf{X} = -\mathbf{F} \rightarrow \begin{bmatrix} \mathbf{J}_{uu} & \mathbf{J}_{up} \\ \mathbf{J}_{pu} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \delta\mathbf{u} \\ \delta\mathbf{p} \end{bmatrix} = - \begin{bmatrix} \mathbf{F}_u \\ \mathbf{F}_p \end{bmatrix}$$

$$\mathbf{B}_U = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{0} & -\mathbf{S} \end{bmatrix}$$



# pTatin3D | Design

- **Flexible solver configurable**

- PCFieldsplit matrix-free

$$\mathbf{J}\delta\mathbf{X} = -\mathbf{F} \rightarrow \begin{bmatrix} \mathbf{J}_{uu} & \mathbf{J}_{up} \\ \mathbf{J}_{pu} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \delta\mathbf{u} \\ \delta\mathbf{p} \end{bmatrix} = - \begin{bmatrix} \mathbf{F}_u \\ \mathbf{F}_p \end{bmatrix}$$

- Schur complement reduction or full-space
- Upper, lower factorizations
- Exact or inexact  $\mathbf{J}_{uu}$  solve
- Matrix type flexibility (Native PETSc MATAIJ or MatShell)
- Portable Extensible Toolkit for Solver Composition

# pTatin3D | Design

- **Minimize memory footprint and maintain robustness**

- **MatNest** —> avoid the copy with `PCFieldSplit`

$$\mathbf{B}_U = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{0} & -\mathbf{S} \end{bmatrix}$$

- Matrix-free kernels via `MatShell`

- Chebyshev as a smoother

- **KSPGCR** —> flexible Krylov method, residual access for free

- **High resolution simulations (large MPI comm. size)**

- Pipelined Krylov methods

- Multigrid on structured grids require repartitioning **PCTelescope**

# pTatin3D | Design

- **History variables discretized via a set of Lagrangian particles**
  - Dedicated object to handle
    - arbitrary data types associated with a particle
    - dynamic sizing / re-sizing of the #particles per MPI rank
  - Dedicated object to handle communication arbitrary particle data
  - This became **DMSwarm**.



# Moving your app. code —> PETSc

- **Discuss your ideas with the developers to**
  - assess feasibility
  - Determine necessary generalizations, abstractions required
  - PCTelescope and DMSwarm required many discussions
- **Benefits**
  - Unload the maintenance burden
  - Reduce the size of your own code base
  - Share your work with others
  - Work with a great project and great people
  - Become a developer one day

# PETSc Rocks

- Is both a statement of what I model using PETSc, and how great PETSc is.
- My software and research would not be possible with PETSc
- My reasons
  - runtime configuration
  - library wide component inter-operability
  - adoption and integration of new contributions from users
  - my CS and math skills improved working with PETSc and its developers
  - development team support